

## How to Predict a Class with Naive Bayes

Task: Predict class of a new sample given the training data

F1	F2	F3	Target
True	Small	False	Class A
False	Medium	False	Class B
True	Small	True	Class B
True	Large	False	Class A

New sample:

False	Medium	True	?
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### 1. Foreach value v in the new sample calculate the probability of v per class

- foreach class X:  $P(\text{value } v \mid \text{class } X) = \frac{\# \text{ of samples with value } v \text{ in Class } X}{\# \text{ of samples in Class } X}$
- e.g.:  $P(F1 = \text{True} \mid \text{Class A}) = 2/2$      $P(F2 = \text{True} \mid \text{Class B}) = 1/2$

### 2. Foreach class calculate the likelihood of the class (given the new sample)

- foreach class X:  $\text{Likelihood}(X \mid E) = P(F1 = \text{True} \mid \text{Class } X) \times P(F2 = \text{Medium} \mid \text{Class } X) \times \dots \times$
- e.g.:  $\text{Likelihood}(\text{Class A} \mid E) = P(F1 = \text{True} \mid \text{Class A}) \times P(F2 = \text{Medium} \mid \text{Class A}) \times P(F3 = \text{True} \mid \text{Class A}) \times P(\text{Class A}) = \frac{2+1}{2+1} \times \frac{0+1}{2+1} \times \frac{0+1}{2+1} \times \frac{2}{4} = 0.05555$
- $P(\text{Class A})$  ... Proportion of the Class A in the training data
- disclaimer: to prevent multiplication with zero a default value of one is added (= Laplace correction)
  - o Laplace correction is not needed for the class Probability  $P(\text{Class } X)$

### 3. Foreach class calculate the probability of the class (given the new sample)

- foreach class X:  $P(X \mid E) = \frac{\text{Likelihood}(X \mid E)}{\text{Likelihood}(\text{AllClasses})}$
- e.g.:  $P(\text{Class A} \mid E) = \frac{\text{Likelihood}(\text{Class A} \mid E)}{\text{Likelihood}(\text{Class A} \mid E) + \text{Likelihood}(\text{Class B} \mid E)}$

### 4. Choose the class with highest probability as predicted class of the new sample

Numerical Values

for numerical values we can calculate mean and sd per class and use the gaussian

density function:  $f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\left(\frac{(x-\mu)^2}{2\sigma^2}\right)}$  to get the probability of the new sample value.

(Step 2-4 are the same)

# How to Build a Decision Tree

Task: Construct a decision tree from a given Sample Set

## 1. For each attribute A identify possible splits of samples into subspaces

- a. a possible split is
  - i. for categorical values: e.g. one vs. all
  - ii. split of continuous variables at values ver
- b. **foreach possible split calculate split score** (Error Rate, Information Gain or Gini Index)
  - i. Absolute Error Rate
    1. Absolute number of False Classified Samples in the Subset
    2. Best Split = Split with lowest error rate
  - ii. Information gain
    1. Compute the Entropy using the probability of each class
      - Entropy =  $H(X) = E(I(X)) = \sum_{i=1}^n p(x_i)I(x_i) = -\sum_{i=1}^n p(x_i) \log_2 p(x_i)$
      - n ... number of classes
      - $p(x_i)$  ... probability of picking a datapoint with class i
    2. Compute Information gain
      - for subset A and B of the Split:
      - $IG(X_A, X_B) = H(X) - p(x_a)H(X_A) - p(x_b)H(X_B)$
      - $H(X)$  ... Entropy of unsplit data
      - $p(x_a)$  ... Probability of Subset A =  $\frac{\# \text{Samples in A}}{\# \text{Samples in A \& B}}$
      - $H(X_A)$  ... Entropy of Subset A (again using all classes)
    3. Best Split = Split with highest information gain
  - iii. Gini index
    1. Compute the Gini Index using the probability of each class
      - Gini index =  $I_G(p) = 1 - \sum_{i=1}^{|C|} p_i^2$
      - C ... total classes
      - $p_i$  ... probability of picking a datapoint with class i
    2. Compute Gini index gain
      - $GG(X_A, X_B) = I_G(X) - p(x_a)I_G(X_A) - p(x_b)I_G(X_B)$
      - $I_G(X)$  ... Gini index of unsplit data
      - $p(x_a)$  ... Probability of Subset A =  $\frac{\# \text{Samples in A}}{\# \text{Samples in A \& B}}$
      - $I_G(X_A)$  ... Gini index of Subset A (again using all classes)
    3. Best Split = Split with highest Gini Gain
- c. choose best split per attribute
- d. choose best split of all attributes

## 2. Split samples into subspaces according to the best split

3. if all subspaces consist of samples of the same classes or max depth is reached stop
4. else start over from 1. with the new subspaces

# How to Construct a Bayesian Network

Case A: Structure known → Learn probabilities

1. Calculated Conditioned Probability of an event using the given data

- e.g.  $P(J|A) = \frac{\# \text{ Samples where } A=\text{true} \wedge J=\text{true}}{\# \text{ Samples } A=\text{true}}$
- add Laplace correction

B	E	A	J	M
t	f	t	t	f
f	f	f	f	t
f	t	f	t	f
...				

Use counts

$P(J|A) = (\#A = \text{true} \wedge J = \text{true}) / \#(A = \text{true})$

Avoid 0 probabilities (Laplace correction):

$P(J|A) = (\#(A = \text{true} \wedge J = \text{true}) + 1) / (\#(A = \text{true}) + 2)$

$P(E) = (\#(E = \text{true}) + 1) / (k + 2)$

k: number of samples

Laplace correction

Case B: Structure not known → Learn Structure and probabilities

Task: find a network that is a good fit to data and has low complexity

→ Maximize  $\log(P(D|M)) - \alpha \#M$

$\alpha$  ... indicates how important complexity reduction is

brute force for finding structure would be computational too expensive → use heuristics (local search, simulated annealing etc.)

for instances with Hill Climbing:

- Construct an initial network
- Calculate the score of the current Bayesian Network (with learned probabilities)
- Create network's neighbourhood by modifying the current network
  - small changes to the current network (e.g. add arc, remove arc, reverse arc)
- Select best of the networks in the neighbourhood as a new current network
- Go to 3. if stop criteria is not fulfilled

## How to do AdaBoost

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- A circular sector divided into 10 equal segments, labeled  $p_1$  through  $p_{10}$  in a clockwise direction starting from the top. The segments are shaded gray. A small black dot is located at the center of the circle.

## How to Build a Rule Set with the Covering Algorithm

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//todo
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1. Fix one class