Programm- & Systemverifikation

Test-Case Generation

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▶ How bugs come into being:

- ▶ **Fault** cause of an error (e.g., mistake in coding)
- ▶ **Error** *incorrect* state that may lead to failure
- ▶ **Failure** deviation from *desired* behaviour
- ▶ We specified *intended* behaviour using **assertions**.
- \triangleright We proved our programs correct (inductive invariants).
- ▶ We learned how to derive test-cases *by hand.*
- ▶ Coverage criteria. How "good" is our test-suite?

Driven by

- ▶ Requirements and specification
- ▶ Assumptions about program behaviour (equivalence classes!)

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Can't we automate the generation of test cases?

```
int power (int x,
           int y)
{
   int r = y * y;return r;
}
```

```
int power (int x,
             int y)
{
   int r = y * y;return r;
}
                       \rightarrow
```


Can you spot the problem?

▶ How are the return values generated?

Can you spot the problem?

- ▶ How are the return values generated?
- ▶ Solution: let's get them from the specification!

▶ Idea: derive test-cases from a *model*

- \blacktriangleright The model captures requirements at a more abstract level
- ▶ The model is *not necessarily* executable
- ▶ The model must be *easier to understand* (more abstract)

Common modelling languages:

- ▶ Unified Modeling Language (UML)
	- ▶ + Object Constraint Language (OCL)
- ▶ Finite State Machines
- \blacktriangleright Matlab/Simulink
- ▶ SCADE/Esterel

▶ . . .

▶ Component diagrams in UML

Illustrates architecture

▶ Class diagrams in UML

 \triangleright Specifies class interfaces and relations

▶ Class diagrams in UML

▶ Specifies class interfaces and relations

▶ Neither component nor class diagrams specify *behaviour!*

▶ Needed for test-case generation!

Activity diagrams

Activity diagrams

- ▶ Describes possible sequences of events
- ▶ Can be used to derive *abstract* test-cases

Test case:

Test case:

▶ Start,

Test case:

 \blacktriangleright Start, parse,

Test case:

 \triangleright Start, parse, find path,

Test case:

▶ Start, parse, find path, generate test-case,

Test case:

▶ Start, parse, find path, generate test-case, check coverage,

Test case:

▶ Start, parse, find path, generate test-case, check coverage, coverage achieved,

Test case:

▶ Start, parse, find path, generate test-case, check coverage, coverage achieved, done.

Challenge: Abstraction level

▶ We generated an *abstract* test-case

- ▶ How can we map it to a concrete test-case?
	- ▶ Implementation may have *more details*
- \blacktriangleright Is there even a corresponding concrete test-case? (feasibility)
- ▶ How can we test the outcome?
- ▶ Can we provide any *coverage* guarantees (for implementation)?

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Maybe we can choose a *less abstract* modelling language?

Modelling Language: Simulink

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 \triangleright To which implementation will we apply the test-suite?

 \triangleright Simulink enables code generation

- \triangleright Simulink enables code generation
- Can you spot the problem?
- What are we testing here?

Don't . . .

- \triangleright extract test-cases ($\stackrel{\text{def}}{=}$ input+output) *from* implementation
- ▶ apply test-cases extracted from model to *generated code*
- ▶ let coverage criteria drive your test-case generation

Don't . . .

- \blacktriangleright extract test-cases ($\stackrel{\text{def}}{=}$ input+output) *from* implementation
- ▶ apply test-cases extracted from model to *generated code*
- ▶ let coverage criteria drive your test-case generation Why?
	- ▶ coverage becomes meaningless as a stopping criterion

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	- ▶ Constrain *behaviour* of program
- ▶ Are there meaningful applications of TCG?
- ▶ Can we "decouple" TCG from the specification?
	- ▶ Assertions are partial *specifications*
	- ▶ Constrain *behaviour* of program
- ▶ Bug hunt! (Assertion violations, crashes...)
	- \blacktriangleright Find inputs that crash the system
	- ▶ No outputs required

- ▶ buffer overflows
- \blacktriangleright division by zero
- ▶ invalid pointer dereferences
- \blacktriangleright assertion violations
- ▶ . . .

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▶ invalid pointer dereferences

 \blacktriangleright assertion violations

 \blacktriangleright . . .

▶ buffer overflows \triangleright assert $(i \lt len); \ldots \preceq [i]$ ▶ division by zero \triangleright assert (y != 0); ... x/y ▶ invalid pointer dereferences

 \blacktriangleright assertion violations

 \blacktriangleright . . .

▶ buffer overflows \triangleright assert $(i \lt len); \ldots \preceq [i]$ ▶ division by zero \triangleright assert $(y := 0); \ldots x/y$ ▶ invalid pointer dereferences \triangleright assert (p != NULL); \ldots *p \blacktriangleright assertion violations \blacktriangleright . . .

When does an assertion assert(*P*); fail?

- ▶ if *P* evaluates to *false*
- ▶ depends on *values of variables, heap, ...*

How do we evaluate *P*?

- \triangleright As specified by language definition
- ▶ Remember lecture on assertions

When does an assertion assert(*P*); fail?

- ▶ if *P* evaluates to *false*
- ▶ depends on *values of variables, heap, ...* (program state)

How do we evaluate *P*?

- \triangleright As specified by language definition
- ▶ Remember lecture on assertions

▶ e.g., syntax for *multiplicative expressions*:

```
multiplicative-expression:
    pm-expression (e.g., a variable)
    multiplicative-expression * pm-expression
    multiplicative-expression / pm-expression
    multiplicative-expression % pm-expression
```
semantics (meaning) of multiplicative operators:

- \triangleright "₃ The binary $*$ operator indicates multiplication"
- \blacktriangleright "₄ The binary / operator yields the quotient, and the binary % operator yields the remainder from the division of the first expression by the second. If the second operand of / or % is zero the behavior is undefined. [. . .]"

What's going to happen next?

- ▶ There are *many* conceivable states violating that assertion
- ▶ We *only need to find one!*

A bit of terminology:

- ▶ An expression *P* is *satisfiable* if there *exists* a valuation of its variables that makes it true.
- ▶ An expression *P* is *unsatisfiable* if there *exists* no valuation of its variables that makes it true.

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A brief quiz: satisfiable or unsatisfiable?

1. (a > b) && (y == a) 2. (a > b) && (a + b == 0) 3. ((a + b) % 2 == 0) && (b & 1) && (a == 0) 4. (a != b) || (a == b)

A bit of terminology:

- ▶ An expression *P* is *satisfiable* if there *exists* a valuation of its variables that makes it true.
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A brief quiz: satisfiable or unsatisfiable?

\n- 1.
$$
(a > b)
$$
 & $(y == a)$
\n- 2. $(a > b)$ & $(a + b == 0)$
\n- 3. $((a + b) \, % \, 2 == 0)$ & $(b \, k \, 1)$ & $(a == 0)$
\n- 4. $(a != b) \, || \, (a == b)$
\n- 5. Multiply the right, this is a 1000.
\n

▶ What's special about this one?

 $((x!=y)||(x&2) == 2)$ && $(y==z+z)$ && $(x==(z<<1))$ && $((z&1) == 0)$

 $((x!=y)||(x&2)=2)$ && $(y==z+z)$ && $(x==(z<<1))$ && $((z&1)==0)$

 \triangleright $(zk1) == 0$, therefore $(z<<1) & 2 == 0$

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 $((x!=y)||(x&2) == 2)$ && $(y==z+z)$ && $(x==(z<<1))$ && $((z&1) == 0)$

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 \triangleright $(z\&1) == 0$, therefore $(z<<1)\&2 == 0$ \blacktriangleright It follows that $x&2==0$ \blacktriangleright y==z+z, therefore y==z<<1 \blacktriangleright It follows that $x = y$

 $((x!=y)||(x&2)=2)$ && $(y==z+z)$ && $(x==(z<<1))$ && $((z&1)==0)$

$$
(z\&1) == 0, therefore (z<<1)\&2 == 0
$$

 \blacktriangleright It follows that $x&2==0$

- \blacktriangleright y==z+z, therefore y==z<<1
	- \blacktriangleright It follows that $x = y$

▶ Therefore, the disjunction $((x!=y)||(x&2)=2)$ is false

▶ Expression is *unsatisfiable*

- \triangleright Manual analysis of these examples is tedious
- ▶ There are *automated decision procedures* for satisfiability
- ▶ e.g., the *Satisfiability Modulo Theory* (SMT) solver *Z3*
	- ▶ <https://github.com/Z3Prover/z3>
	- \blacktriangleright (there'll be a separate lecture on SMT solvers)

\triangleright Unfortunately, Z3 doesn't speak C++

- \blacktriangleright Need to translate our input
- ▶ Front end simplicity over "linguistic convenience"
- \blacktriangleright Uses *polish notation*, i.e., $(+ 3 4)$ instead of $3 + 4$
- ▶ Tutorial on

<https://github.com/Z3Prover/z3/wiki#background>

 \triangleright Variables need to be declared and typed:

- ▶ (declare-const p Bool)
- ▶ (declare-const q Bool)

("variables" in Z3 are constants/null-ary functions)

▶ We can add "assertions" over declared variables

▶ (assert (or p q))

 \triangleright We can check satisfiability

▶ (check-sat)

- ▶ We can ask for a *model*
	- ▶ (get-model)

```
(declare-const p Bool)
(declare-const q Bool)
(assert (or p q))
(check-sat)
(get-model)
```
And the answer is:

```
sat
(model
  (define-fun q () Bool
   false)
  (define-fun p () Bool
 true)
)
```
The answer is:

```
sat
(model
  (define-fun q () Bool
   false)
  (define-fun p () Bool
 true)
)
```
▶ Remember: Variables are constants/null-ary functions

- ▶ A null-ary function has *no* parameters
- \blacktriangleright Returns a value
- \blacktriangleright In this context, just like a variable

```
(declare-const p Bool)
(declare-const q Bool)
(\text{assert } (\text{and } (\text{or } p q) \ (\text{and } (\text{not } p) \ (\text{not } q))))(check-sat)
```
 \triangleright And the answer is ... unsat

▶ SMT-Solvers/Z3 can do more than just propositional logic

- ▶ Arithmetic
- ▶ "Uninterpreted" functions
- ▶ Arrays
- ▶ Bit-Vectors
- \blacktriangleright ...

▶ Binary and hexadecimal constants:

 \blacktriangleright #b0100

 \blacktriangleright #x0a

▶ Declare "variables" of type bit-vector:

 \blacktriangleright (declare-const x (BitVec 16))

 \blacktriangleright (declare-const y (BitVec 16))

 \blacktriangleright Bit-vector operations

 \triangleright (byadd x #x0001) denotes $x + 1$

▶ (bvsub x y) denotes *^x* − *^y*

▶ (bvneg x) denotes −*^x*

▶ (bvmul x y) denotes *^x* ∗ *^y*

 \triangleright (bvshl x #x0001) denotes $x \lt\lt 1$ (shift-left)

 \blacktriangleright . . .

▶ Binary and hexadecimal constants:

- \blacktriangleright #b0100 (this is decimal 4)
- \blacktriangleright #x0a
- ▶ Declare "variables" of type bit-vector:
	- \blacktriangleright (declare-const x (BitVec 16))
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- \blacktriangleright Bit-vector operations
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	- \blacktriangleright . . .

▶ Binary and hexadecimal constants:

- \blacktriangleright #b0100 (this is decimal 4)
- \blacktriangleright #x0a (this is decimal 10)
- ▶ Declare "variables" of type bit-vector:
	- \blacktriangleright (declare-const x (BitVec 16))
	- \blacktriangleright (declare-const y (BitVec 16))
- \blacktriangleright Bit-vector operations
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	- \triangleright (bvshl x #x0001) denotes $x \lt\lt 1$ (shift-left)
	- \blacktriangleright . . .
```
(declare-const x (_ BitVec 16))
(declare-const y (_ BitVec 16))
(declare-const z (_ BitVec 16))
(assert
  (and
    (or
       (not (= x y))( = (bvand x #x0002) #x0002)
    )
    (= y (bvadd z z))(= x \text{ (bushl z #x0001)})(= (bvand z #x0001) #x0000)
  )
)
(check-sat)
```

```
assert (a[i]>pi);
```

```
▶ i=0, pi=3.14, a=\{0.0\} satisfies ! (a[i]>pi)
```

```
const float pi = 3.14;
float a[] = \{4.0, 4.0\};int i = 0;
assert (a[i]>pi);
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const float pi = 3.14; \downarrow (pi=3.14)
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const float pi = 3.14; \downarrow (pi=3.14)
float a[] = \{4.0, 4.0\}; \quad \downarrow (a[0] = 4.0) \& (a[1] = 4.0))int i = 0;
assert (a[i]>pi);
```

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assert (a[i]>pi);
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const float pi = 3.14; \downarrow (pi=3.14)
\texttt{float a[] = } \{4.0\, , \; 4.0\}; \quad \quad \downarrow \bigl(a[0]\texttt{=}4.0) \texttt{\&\&\&\&\&\&\,.0\bigr)}int i = 0;
assert (a[i]>pi);
                                            \pm (i=0)
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assert (a[i]>pi);
                                            \downarrow (i=0)
                                            |!(a[i]>pi)
```
\blacktriangleright Is $(pi==3.14)$ && $(a[0]=-4.0)$ && $(a[1]=-4.0)$ && $(i==0)$ &&!(a[i]>pi) satisfiable?

\blacktriangleright Is

$(pi==3.14)$ && $(a[0]=-4.0)$ && $(a[1]=-4.0)$ && $(i==0)$ &&!(a[i]>pi)

satisfiable?

▶ No!

```
int i;
const float pi = 3.14;
float a[] = \{1.0, 5.0\};assert (a[i]>pi);
```

```
int i;
const float pi = 3.14;
float a[] = \{1.0, 5.0\};assert (a[i]>pi);
                                \downarrow (i=?)
```

```
int i;
const float pi = 3.14;
float a[] = \{1.0, 5.0\};assert (a[i]>pi);
                             (i=?)(pi=3.14)
```

```
int i;
const float pi = 3.14; \downarrow (pi=3.14)
float a [] = {1.0 , 5.0};
(a[0]=1.0)&&(a[1]=5.0))
assert (a[i]>pi);
                               \downarrow (i=?)
```

```
int i;
const float pi = 3.14; \downarrow (pi=3.14)
float a[] = {1.0, 5.0}; \downarrow (a[0]=1.0)&&(a[1]=5.0))
assert (a[i] > pi);
                                  \downarrow (i=?)
                                 \lfloor!(a[i]>pi)
```
 \blacktriangleright Let i be an uninitialised variable (or user input)

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int i;
const float pi = 3.14; \downarrow (pi=3.14)
assert (a[i] > pi);
```

```
float a[] = {1.0, 5.0}; \downarrow (a[0]=1.0)&&(a[1]=5.0))
                                    \downarrow (i=?)
                                    \lfloor! (a[i]>pi)
```
 \blacktriangleright i's value is "undetermined" ▶ Could be any int value

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float a[] = {1.0, 5.0}; \downarrow (a[0]=1.0)&&(a[1]=5.0))
assert (a[i] > pi);
                                 \downarrow (i=?)
                                |!(a[i]>pi)
```
 \blacktriangleright i's value is "undetermined"

▶ Could be any int value

▶ Assertion violated if we choose i to be 0

▶ Concrete values:

Actual values a variable or data-structure could take during execution, e.g., $1, 2, -3.14$, true, "Hello world", ...

▶ Symbolic values:

Placeholder values (undetermined values), representing, for instance, user input

 \blacktriangleright Let's use x_0 to denote *symbolic values* of x

 \triangleright Which input value makes the following function fail?

```
int foo(int x){
  int y = x + 1;
  assert (y != 0);
  return (x/y);}
```
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int foo (int x )
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}
                         x \mapsto x_0
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}
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int foo (int x){
   int y = x + 1;
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                           x \mapsto x_0y \mapsto x_0 + 1(x_0 + 1 \neq 0)
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```
▶ Representation of *an equivalence class of executions* \triangleright for *all possible values of* x (represented by x_0)

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▶ Representation of *an equivalence class of executions* \triangleright for *all possible values of* x (represented by x_0) \triangleright Can we make this "symbolic" execution fail?

- \blacktriangleright Let's use x_0 to denote *symbolic values* of x
- \triangleright Which input value makes the following function fail?

```
int foo(int x){
  int y = x + 1;
  assert ( y !=0) ;
  return (x/y);
}
                           x \mapsto x_0y \mapsto x_0 + 1!(x_0 + 1 \neq 0)
```
▶ Representation of *an equivalence class of executions* \triangleright for *all possible values of* x (represented by x_0) \triangleright Can we make this "symbolic" execution fail?

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- \triangleright Which input value makes the following function fail?

```
int f \circ \circ (\text{int } x){
   int y = x + 1;
   assert ( y !=0) ;
  return (x/y);
}
                                x \mapsto x_0y \mapsto x_0 + 1!(x_0 + 1 \neq 0)
```
▶ Representation of *an equivalence class of executions* \triangleright for *all possible values of* x (represented by x_0) \triangleright Can we make this "symbolic" execution fail? Ask the SMT solver whether $!(x_0 + 1 \neq 0)$ is satisfiable

```
void bar(int x){
  int y = x + 1;
  if (x > -1)y = y + 1;assert (y != 0);
}
```

```
void bar(int x){
  int y = x + 1;
  if (x > -1)y = y + 1;assert (y != 0);
}
                        \vert x \mapsto x_0
```

```
void bar(int x){
   int y = x + 1; \qquad \qquad \downarrow y \mapsto x_0 + 1if (x > -1)y = y + 1;assert (y != 0);
}
                               \downarrow x \mapsto x_0
```

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void bar(int x){
  int y = x + 1;
  if (x > -1)y = y + 1;
  assert (y != 0);
}
                         x \mapsto x_0y \mapsto x_0 + 1(x_0 > -1)
```

```
void bar(int x){
  int y = x + 1;
  if (x > -1)y = y + 1; y \mapsto x_0 + 2assert (y != 0);
}
                         x \mapsto x_0y \mapsto x_0 + 1(x_0 > -1)
```

```
void bar (int x )
{
   int y = x + 1;
   if (x > -1)y = y + 1;
   assert ( y !=0) ;
}
                            x \mapsto x_0y \mapsto x_0 + 1(x_0 > -1)y \mapsto x_0 + 2(x_0 + 2 \neq 0)
```

```
void bar (int x )
{
  int y = x + 1;
  if (x > -1)y = y + 1; y \mapsto x_0 + 2assert (y!=0); \qquad\downarrow!(x_0 + 2 \neq 0)}
                           x \mapsto x_0y \mapsto x_0 + 1(x_0 > -1)
```

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void bar (int x )
{
  int y = x + 1;
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                           x \mapsto x_0y \mapsto x_0 + 1(x_0 > -1)
```

```
void bar (int x)
{
   int y = x + 1;
   if (x > -1)y = y + 1;
   assert ( y !=0) ;
}
                           x \mapsto x_0y \mapsto x_0 + 1(x_0 > -1)y \mapsto x_0 + 2!(x_0 + 2 \neq 0)
```
 \triangleright All conditions along the path must be satisfied

```
void bar(int x){
  int y = x + 1;
  if (x > -1)y = y + 1;
  assert ( y !=0) ;
}
                           x \mapsto x_0y \mapsto x_0 + 1(x_0 > -1)y \mapsto x_0 + 2!(x_0 + 2 \neq 0)
```
 \triangleright All conditions along the path must be satisfied

▶ Ask the SMT solver whether

$$
(x_0 > -1) \&\& \cdot \cdot (x_0 + 2 \neq 0)
$$

is satisfiable

```
void bar(int x){
  int y = x + 1;
  if (x > -1)y = y + 1; y \mapsto x_0 + 2assert (y!=0); \qquad\downarrow!(x_0 + 2 \neq 0)}
                          x \mapsto x_0y \mapsto x_0 + 1(x_0 > -1)
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 \triangleright What if we take the else-branch?

```
void bar(int x){
  int y = x + 1;
  if (x > -1)y = y + 1;assert (y != 0);
}
```
```
void bar (int x)
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  int y = x + 1;
  if (x > -1)y = y + 1;assert (y != 0);
}
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```

```
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```

```
void bar (int x)
{
   int y = x + 1; \qquad \qquad \downarrow y \mapsto x_0 + 1if (x > -1) \downarrow (x<sub>0</sub> ≤ −1)
     y = y + 1;assert (y != 0);
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 $▶$ It is $(x_0 = -1)$, therefore assertion can be violated

- ➀ Perform *symbolic* execution of path
- ➁ At any assertion:
	- ▶ ask SMT solver for input assignment violating it

Symbolic Execution Trees

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Explore paths; search for reachable assertions

▶ Some paths are *infeasible*

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- ▶ Some conditions are *implied* (e.g., $(x_0 \le 0)$ \Rightarrow $(x_0 \le 5)$)

▶ *Infeasible* paths don't need to be explored further

- \blacktriangleright Reduces number of paths
- ▶ *Implied* conditions can be dropped
	- ▶ Makes problem for SMT solver easier

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- \blacktriangleright Reduces number of paths
- ▶ *Implied* conditions can be dropped
	- ▶ Makes problem for SMT solver easier
- ▶ Two different concerns:

Path explosion **Path** constraint solving (will address this now) (see lectures end of April) ▶ How many *paths* in this function:

```
for (int i = 0; i < N; i++){
  char ch = getchar();
  if (ch == ' '')space ++;
  else
     other ++;
}
```
▶ Naïve exploration quickly becomes a problem!

▶ How many *paths* in this function:

```
for (int i = 0; i < N; i++){
  char ch = getchar();
  if (ch == ' '')space ++;
  else
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}
```
▶ Naïve exploration quickly becomes a problem!

▶ Solution: search heuristics!

Search heuristics:

- ▶ Breadth-First Search (BFS)
- ▶ Depth-First Search (DFS)
- ▶ Coverage-optimised search (Best-First)
	- ▶ "best" paths increase coverage
- \blacktriangleright Random selection/expansion

Search Heuristics: BFS

 \triangleright Don't explore paths of length $k + 1$ before all paths of length k are explored

Search Heuristics: DFS

 \blacktriangleright Follow path to the end before you explore a new one

Which (incomplete) path in the search tree do we expand next?

- ▶ Expand path "close" to an uncovered instruction
- ▶ Favour paths that recently visited *new* code

Which (incomplete) path in the search tree do we expand next?

- ▶ Randomly choose one
- ▶ "Shorter paths" have higher probability
	- ▶ Avoids starvation (e.g., symbolic loop)

- \triangleright e.g., multiple heuristics in round-robin fashion
- ▶ implemented by KLEE (<http://klee.llvm.org>)

▶ Eliminate *redundant paths*

▶ paths that reach same program location with same constraints

▶ *merge* paths that reach same program location

▶ covered in more detail towards the end of the course

▶ We used TCG to detect assertion violations

 \blacktriangleright Therefore, can also be used to check contract!

```
float sqrt (float x);
pre: x \geq 0post: |result^2 - x| < \varepsilon
```
- ➀ Generate new test-case *from implementation*
- ➁ Check whether input satisfies pre-condition
- ➂ If yes, check whether output satisfies post-condition

▶ Alternatively, we can as an *oracle* for correct output

▶ The *oracle* could be

▶ . . .

- \blacktriangleright a less efficient (but correct) implementation
- \blacktriangleright an executable specification
- ➀ Generate new test-case *from implementation*
- ➁ Run *oracle* with the generated input
- ➂ Compare output of oracle and implementation

- ▶ But dangerous if applied *na¨ıvely*
	- ▶ Outputs *must* be derived from specification
	- ▶ Should not be driven by coverage!
	- ▶ However, can be applied if outputs are not needed (e.g., crash detection, assertion violations)