

187.A27 VU Design Studies

11. Ingenieurwiss. u. kognitiver Ansatz

Descriptive Design Research

- empirische Untersuchung – Designexperiment
- Untersuchungsergebnisse
- Analysing (video-recorded) designing
- Protocol Analysis
- FBS ontology
 - UE: FBS – coding
 - LINKODER
 - Maße

11. Descriptive Design Research

Analysing (video-recorded) designing

Protocol Analysis

- FBS ontology
 - FBS coding UE
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<http://www.linkoder.com/>

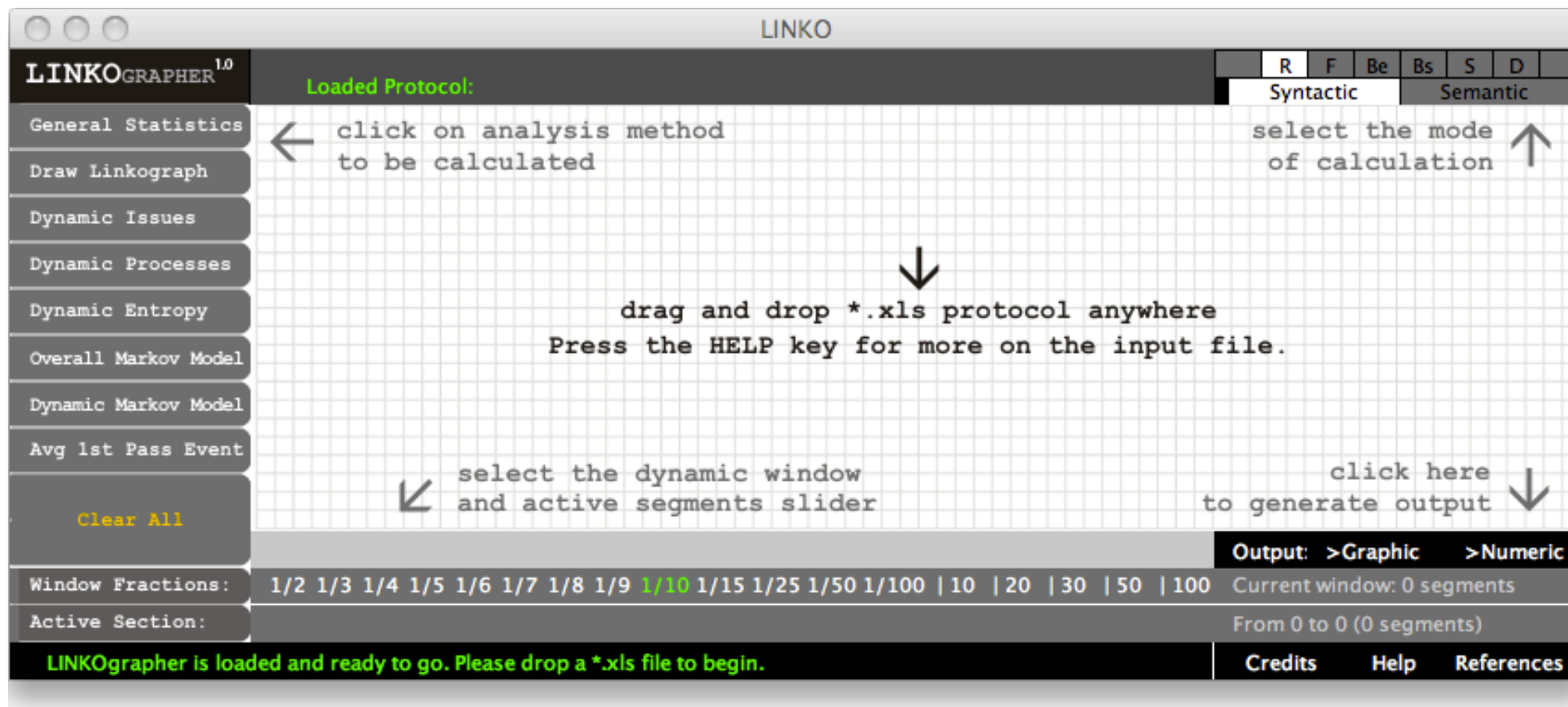
Data input for LINKODER coded segments, links (excel spreadsheet)

1	NUMBER	UTTERANCE	CODE	LINKS					
2	1	J: I ended up with the (.) hold on (2.2) sledge	S						
3	2	A: the sledge excellent so what did that generate then? ((write: sledge))	D	1					
4	3	J: well the sledge manages to keep level by having quite a wide base	Bs	1					
5	4	A: ((write: wide base))	D	3					
6	5	J: and then a main force in the middle so	Bs	3	1				
7	6	J: unlike the set of skis	S	3	1				
8	7	J: where quite narrow and	S	6	3	1			
9	8	J: you go up on an edge- when you're turning	Bs	7	6	5	3	1	
10	9	J: the sledge is er quite broad	S	7	6	3	1		
11	10	J: and then you have the weight right in the middle	Bs	9	6	5	3	1	
12	11	J: so they manage to keep both runners on the snow-	Bs	10	9	8	5	3	1
13	12	A: ((write: force in middle))	D	10	5				
14	13	J: more often than say a sledge or a snowboard- a skis or snowboard	Be	10	9	1			
15	14	A: some some guiders almost down the side of this	S	13	1				
16	15	J: well I guess the easiest way to keep the pen at a right angle would be	Be						
17	16	J: to have a set of stabilisers on it based on the idea of a sledge	S	15	9	3	1		
18	17	A: yeah no problem (.) stabilisers (6) like a bicycle yeah that's a good	S	16					
19	18	A: ((write: stabilizer))	D	16					

reliability

Coding1 vs Arbitrated (%)	Coding2 vs Arbitrated (%)
85.1	89.3

<http://www.linkoder.com/>



Descriptive statistics

- Segment and link counts
- Design issue distribution
- Issue Activity (X) means for distribution of link nodes
- Link Distance (Y) in both vertical and horizontal axes
how far the linked segments are apart
- Design process distribution
- Backlink / Forelink counts
- Backlinks-, Forelinks-, Horizonlinks - entropy

LINKODER - measurement tool

analysis methods

- standard statistical analyses
 - issues distribution
 - dynamic issues distribution
 - process distribution
 - dynamic process distribution
- Markov model generation
- dynamic Markov model generation
- entropy model generation
- dynamic entropy model generation
- drawing of linkograph

LINKODER													
Revision 13/07/2011		Loaded Protocol: DTRSextract1_coded.xls										Statistics	
General Statistics		Total Segments: 18		Issue Distribution (%)		Process Distribution Syntactic (%)		Semantic (%)					
Draw Linkograph		Non-FBS Segments: 0 (% 0)		R	0 (0,0)	Formulation		0 (0,0)	0 (0,0)				
Dynamic Issues		Total Links: 43 (2,39 per seg)		F	0 (0,0)	Synthesis		2 (22,2)	2 (13,3)				
Dynamic Processes		Issue Activity (X)		Be	2 (11,1)	Analysis		2 (22,2)	5 (33,3)				
Dynamic Entropy		Mean 7,7	STD 3,6	Bs	5 (27,8)	Evaluation		0 (0,0)	1 (6,7)				
Overall Markov Model		Link Distance (Y)		S	7 (38,9)	Documentation		2 (22,2)	1 (6,7)				
Dynamic Markov Model		Mean 4,7	STD 3,7	D	4 (22,2)	Reformulation I		2 (22,2)	5 (33,3)				
Avg 1st Pass Event		Forelinks		Backlinks		Horizonlinks		Reformulation II	1 (11,1)	1 (6,7)			
Clear All		Entropy: 8,392		12,326		10,612		Reformulation III	0 (0,0)	0 (0,0)			
General statistics from segment 1 to 18.										Output: >Graphic >Numeric			
Window Fractions:		1/2 1/3 1/4 1/5 1/6 1/7 1/8 1/9 1/10 1/15 1/25 1/50 1/100 10 20 30 50 100											Current window 2 segments
Active Section:		From 1 to 18 (18 segments)											
DTRSextract1_coded.xls has been read with 18 segments, including 18 FBS issues and 43 links										Credits Help References			

Extract: engineering design meeting1

Issue distribution, distribution of codes

engineering design meeting1

Code	Segment	
R	7	1.6%
F	17	3.8%
Bs	126	28.1%
Be	69	15.4%
S	180	40.2%
D	49	10.9%
Total	445	100%

semantic process distribution

FBS processes derived from the links of the coded segments,
engineering design meeting1

Processes		Occurrence	Percentage
Formulation	R>F,F>Be	14	1.4
Synthesis	Be>S	68	6.9
Analysis	S>Bs	120	12.2
Documentation	S>D	52	5.3
Evaluation	Be<>Bs	48(Be>Bs),49(Bs>Be)97	9.9
Reformulation I	S>S	262	26.7
Reformulation II	S>Be	32	3.3
Reformulation II	S>F	1	0.1
	Total	646	65.9

problem-/solution focused designing styles

single-value measurement to summarize the designing style of an entire design session.

The **problem-solution (P-S) index** is ... the ratio of the total occurrences of the design issues concerned with the problem space to the sum of those related to the solution space:

$$\text{P-S index} = \frac{\Sigma (\text{Problem-related issues})}{\Sigma (\text{Solution-related issues})} = \frac{\Sigma (R, F, Be)}{\Sigma (Bs, S)}$$

We define a design session with

P-S index > 1 as one with a problem-focused designing style,

P-S index value ≤ 1 as one with a solution-focused style. (4)

Problem/solution space	Design issue
Problem space = Problem-focused design issues	Requirement (R) Function (F) Expected Behavior (Be)
Solution space = Solution-focused design issues	Behavior from Structure (Bs) Structure (S)

problem-/solution focused designing styles

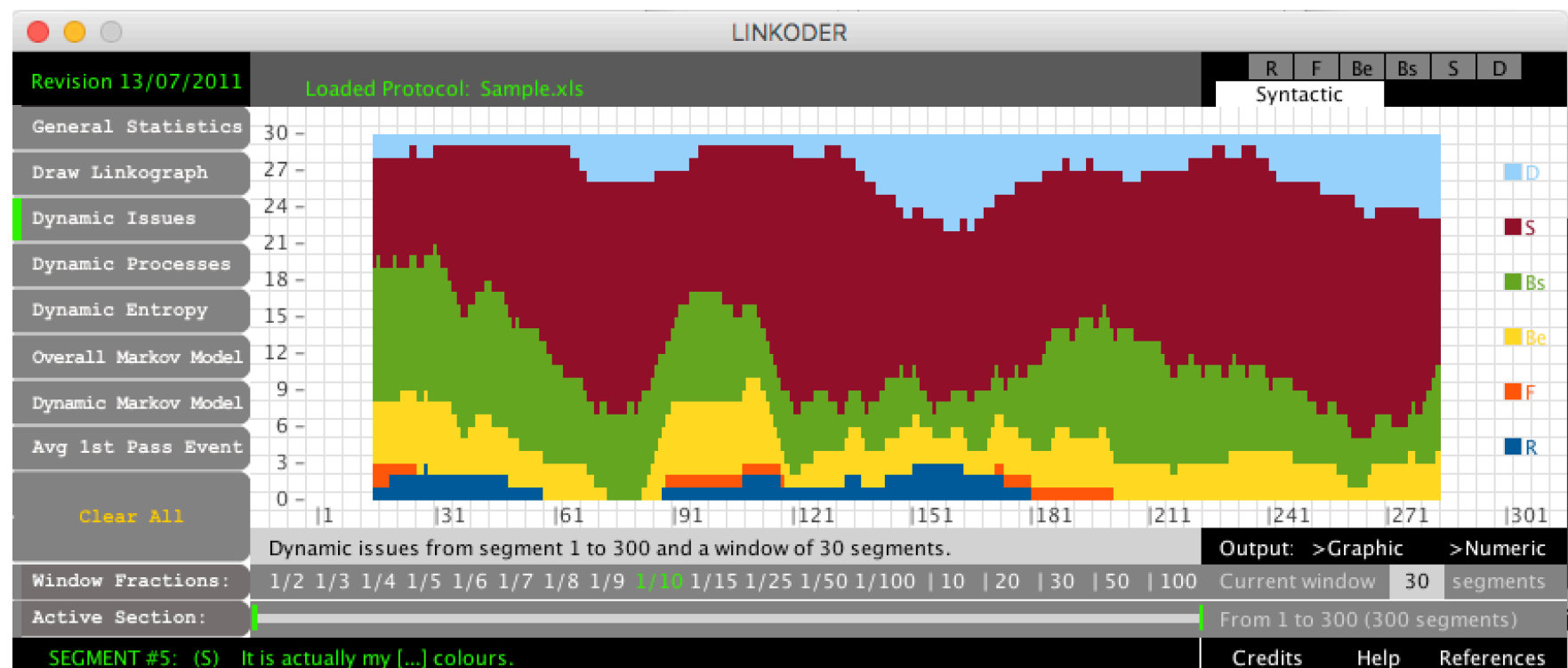
Sequential Problem-Solution index across design session

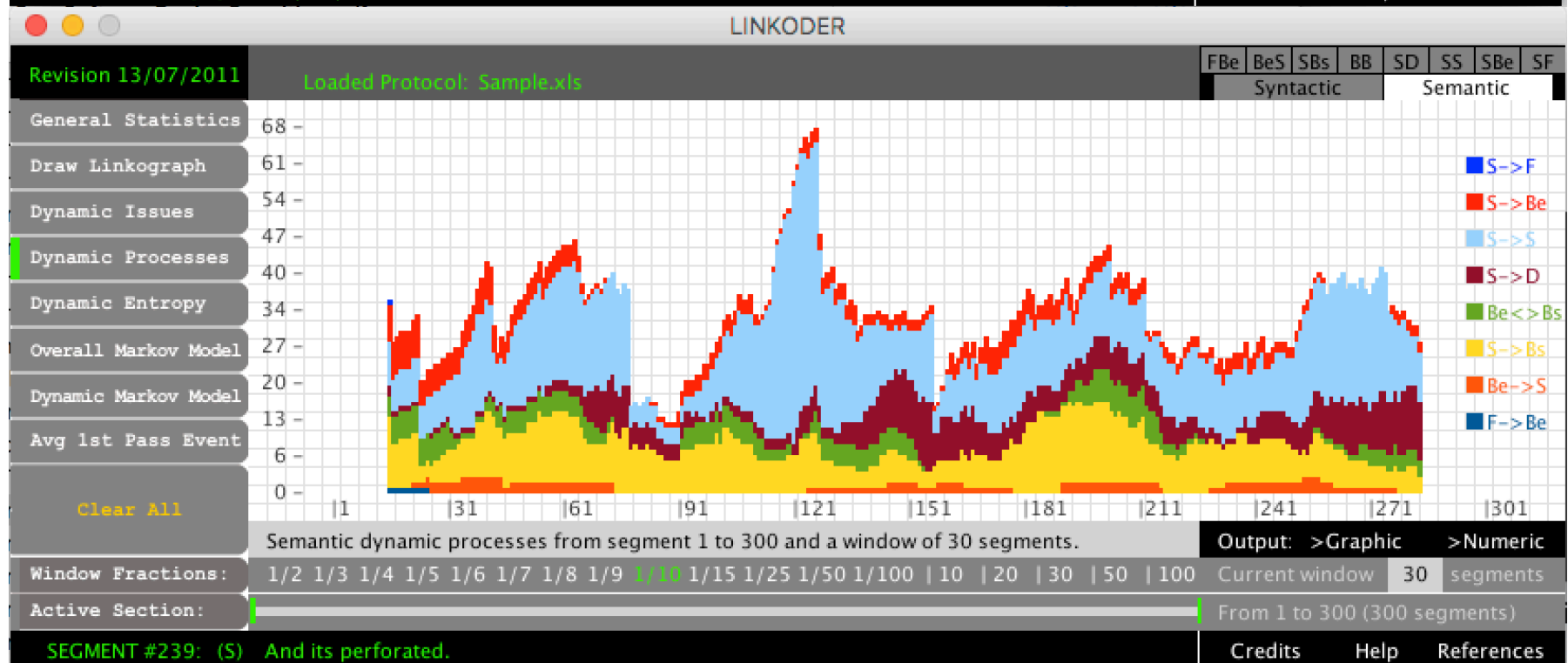
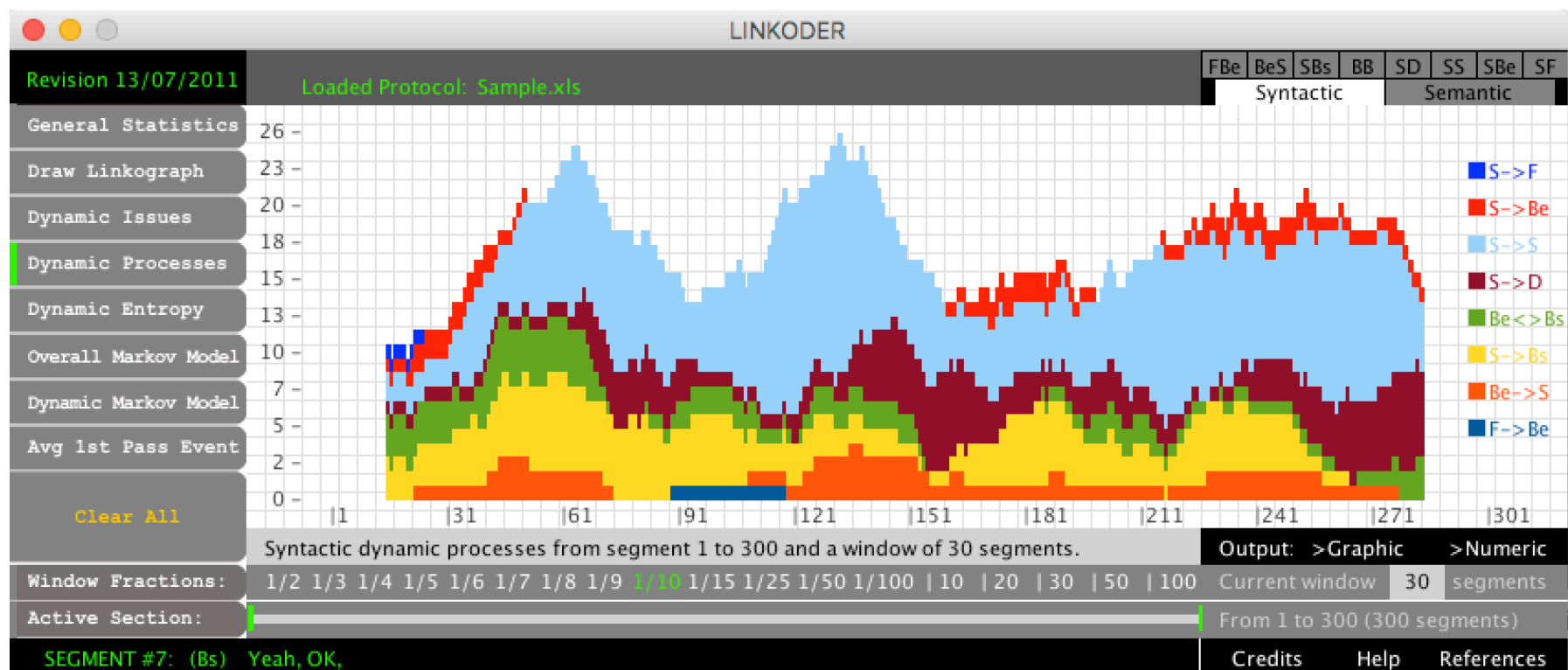
the entire design session is divided - **fractioned into 10** consecutive non-overlapping **sections** each with an equal number of design issues. The P-S index for each section is calculated. A **sequence of temporally ordered P-S indexes** is read as a “signature” of dynamic designing **style**.

$$\text{P-S index} = \frac{\Sigma (\text{Problem-related issues})}{\Sigma (\text{Solution-related issues})} = \frac{\Sigma (R, F, Be)}{\Sigma (Bs, S)}$$

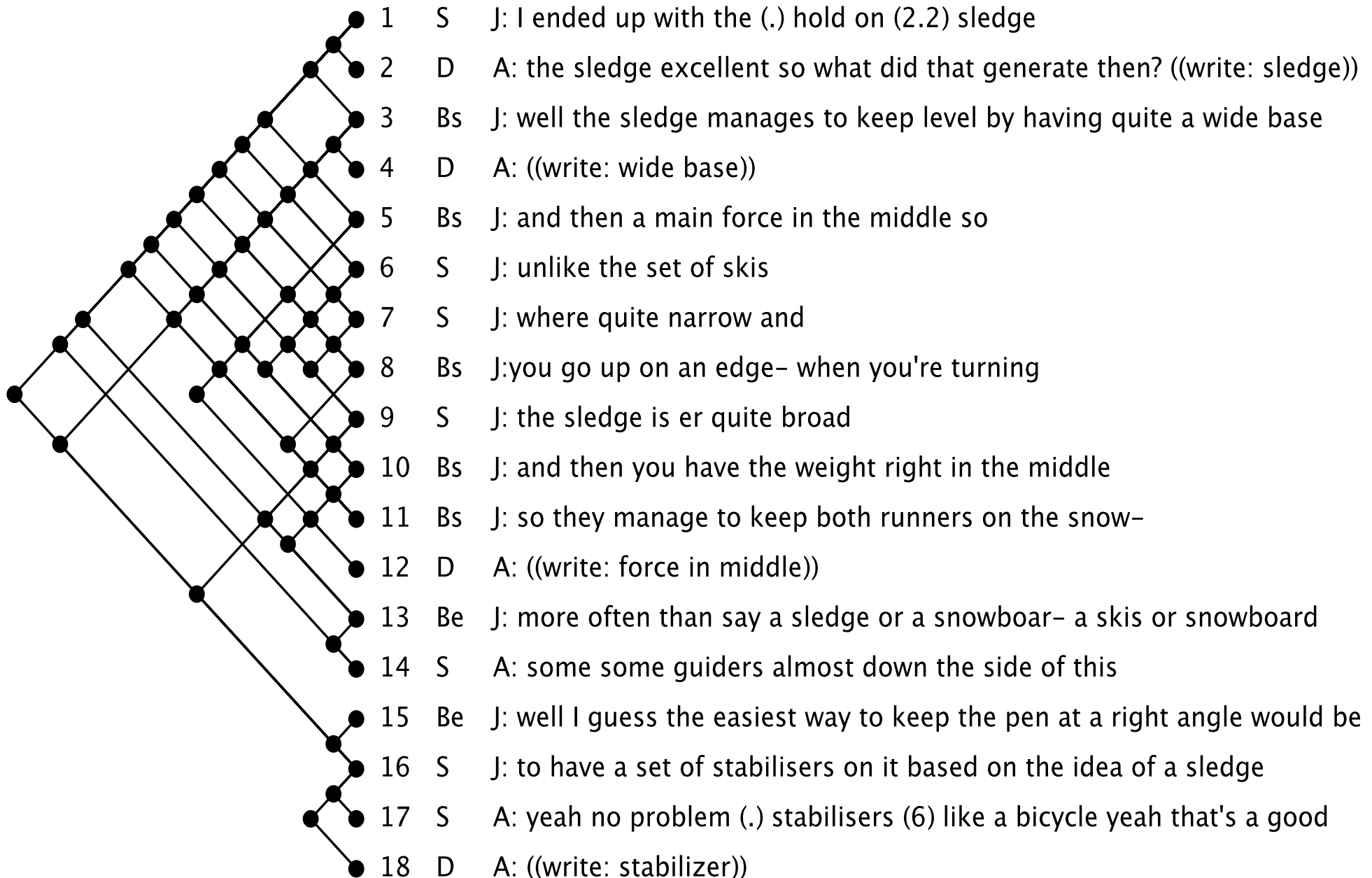
Jiang Gero & Yen: Exploring Designing Styles Using a Problem-Solution Division. DCC'12.

Gero, et al. 2013: Design cognition differences when using unstructured, partially structured, and structured concept generation creativity techniques." Int. J .Design Creativity & Innovation



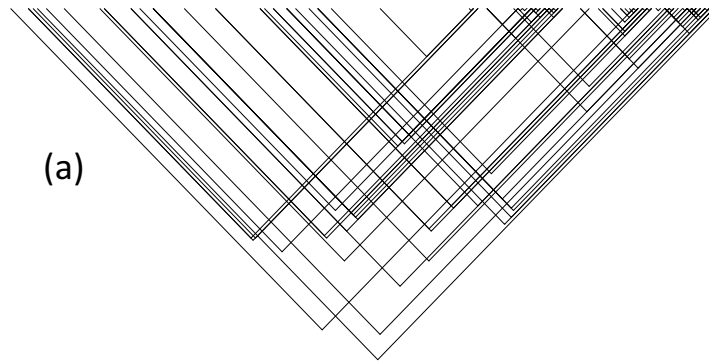


Linkograph

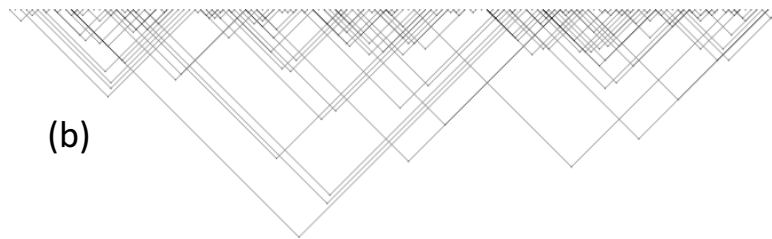


shape of a Linkograph

The design process ... (as) patterns of moves associations.
With the linkograph, we can trace the structure of reasoning.



(a) reflects a relatively **holistic design process** (the linkograph is well integrated)

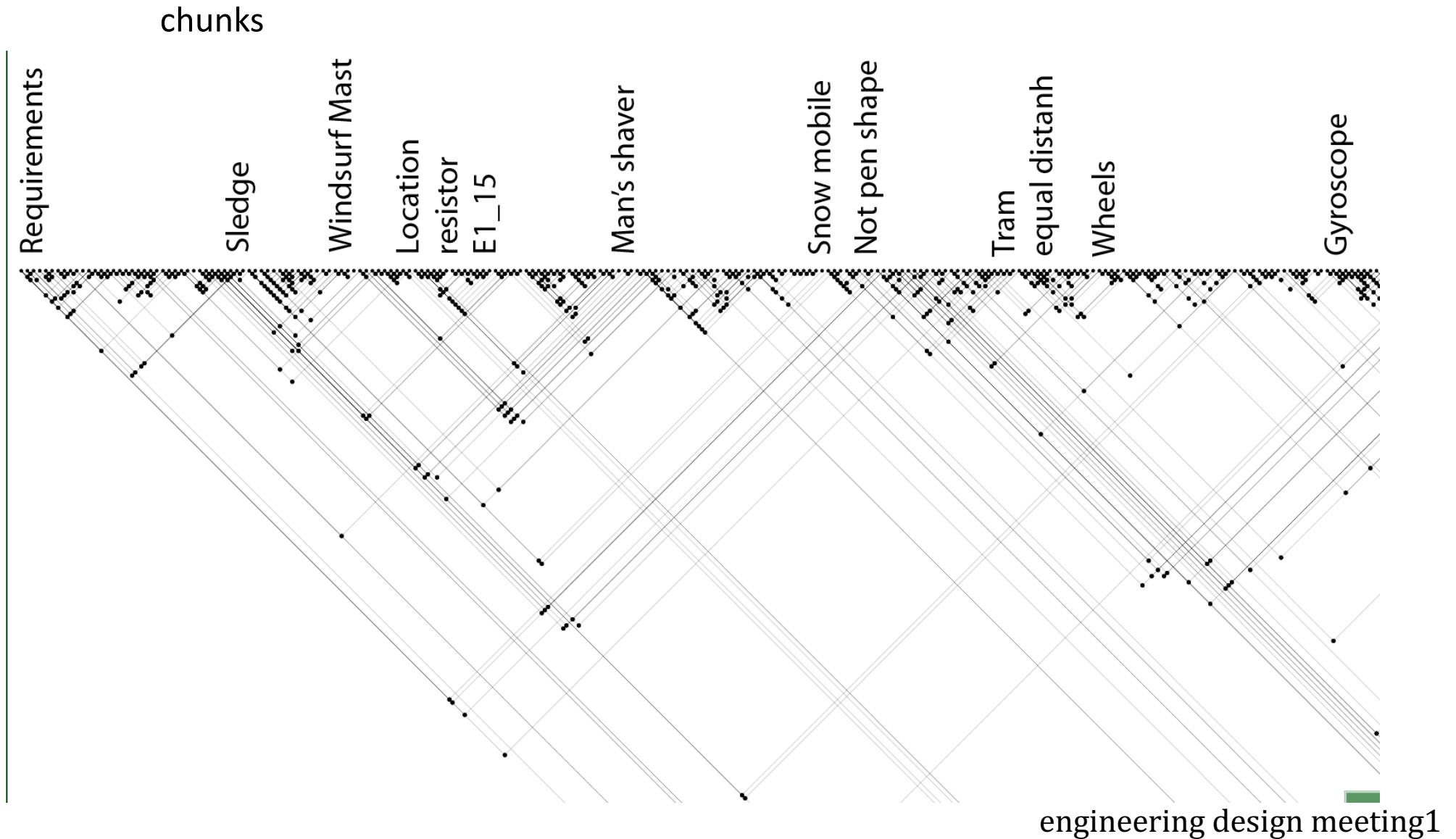


(b) represents a process of **trying out different options** (there are obvious clusters in the linkograph)

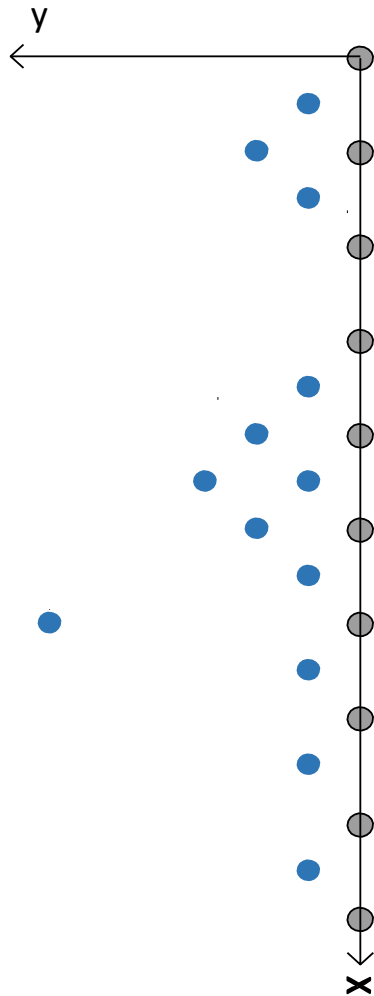
Kan, Bilda & Gero: Comparing Entropy Measure Of Idea Links In Design Protocols. DCC06.

Kan & Gero 2009: Using the FBS Ontology to Capture Semantic Design Info in Design Protocol St.

Part of the linkograph of the segmented protocol



Statistical Description of Linkograph



consider the nodes (but not the moves /segments) in a two dimension space.

Treating each node as a point in the X-Y plane we can statistically describe a linkograph in terms of the

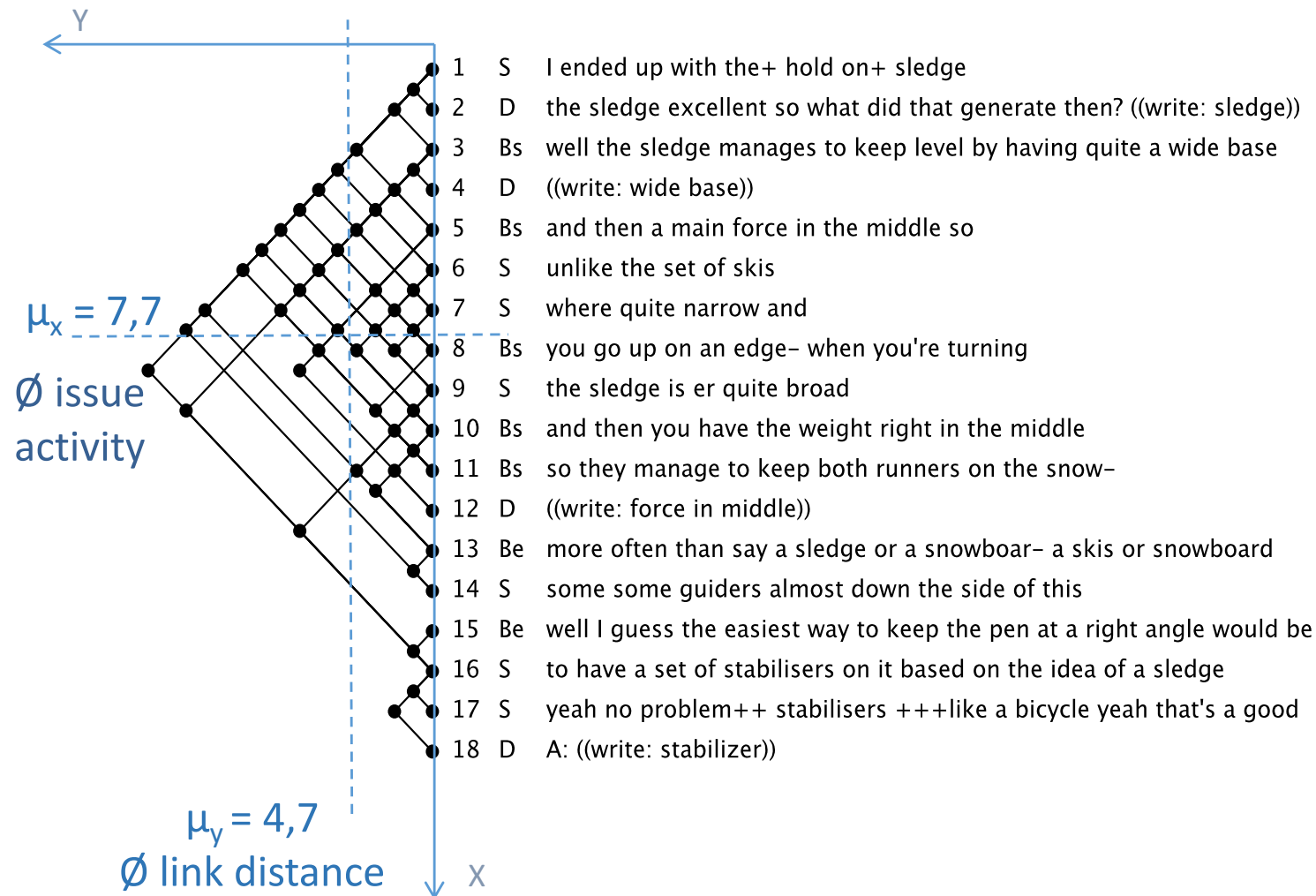
- **total number of nodes** (Links count)
- **mean values of X and Y** – average position (centroid) of all nodes (issue activity; link distance)
- **deviations** in the X and Y axes.

A higher/lower mean value of X implies that more nodes appear at the end/beginning of a session.

A higher mean value of Y indicates longer linking lengths.

LINKODER – basic descriptive statistics

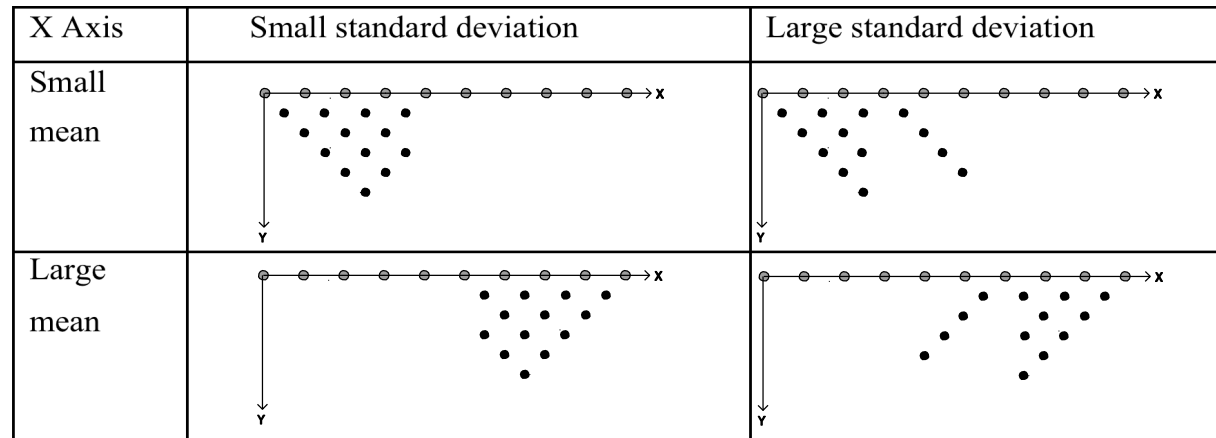
issue activity (X); link distance (Y)



shape of a Linkograph

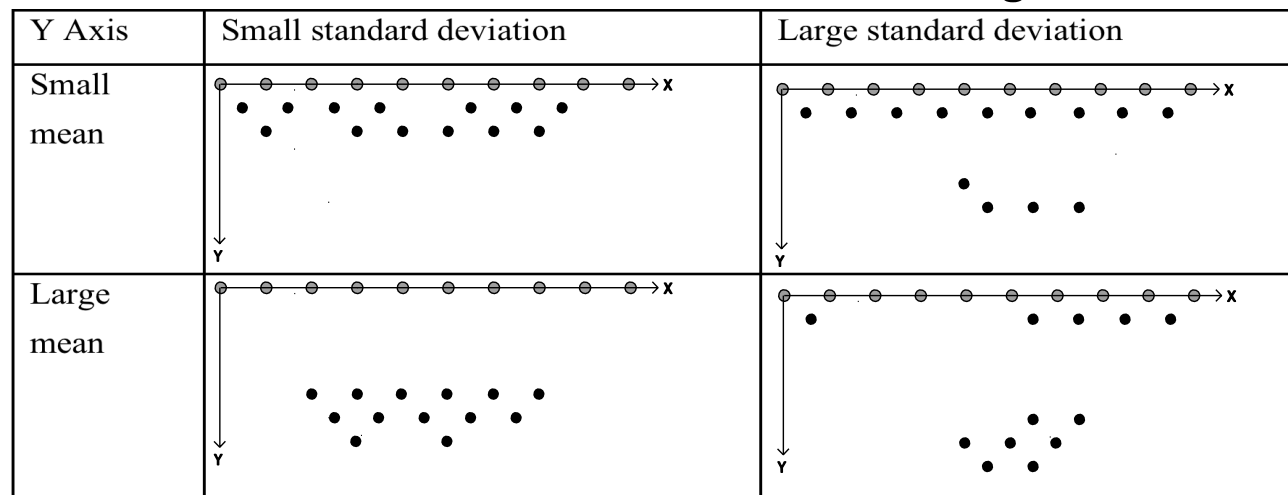
issue activity (X); link distance (Y)

with the same number of nodes, in relation to mean and standard deviation of **X**.
A higher value of X-mean signifies - more **activities at** the end of the session.



Standard deviations:
how concentrated the
nodes are clustered
around the means.
The lower the value
the closer those nodes
are toward the mean

same number of nodes, in relation to mean and standard deviation of **Y**.
A lower value of Y-mean indicates shorter **linking distance**.



Link index, critical moves - **design productivity**

General statistics from segment 1 to 18

Total Segments:	18
Non-FBS Segments:	0 (0%)
Total Links:	43 (2,39 per seg)

$$\text{Link index} = \frac{\text{number of links}}{\text{number of segments/moves}} = \text{links per seg.}$$

“Link Index is a measure of **how connected** the **design ideas are** in a design session.”

A higher value of Link index and critical moves indicates more **productive design process**.

(leading to “successful products” (Goldschmidt: Criteria...))

Critical Moves (CM)

CM = design moves /segments that are rich in links

CM = moves that generate a **higher number of links** (backward or forward).

“CM identifies design concepts that are deemed ‘successful’ in the sense that the designer values them enough to devote time trying to develop the concepts ...”. Goldschmidt (2003) established a

‘critical move’ threshold criterion:

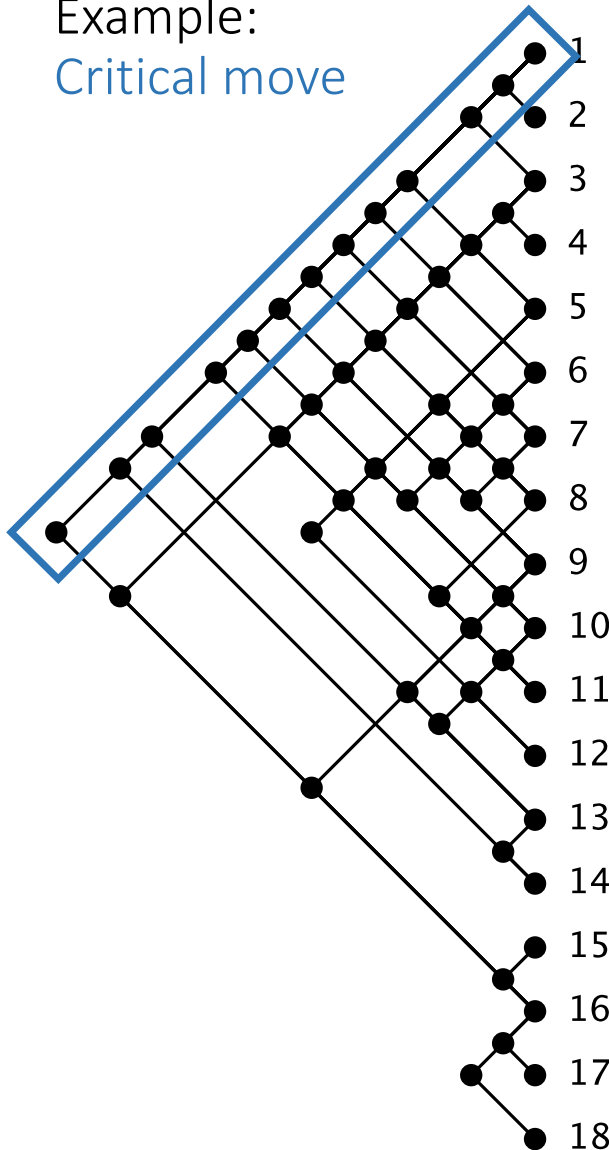
a move/segment that varies between 5 and 8 links;

number of CM < 10% of number of moves

CMⁱ = a critical move carrying ‘i’ number of links.

Linkograph

Example:
Critical move



- 1 S J: I ended up with the (.) hold on (2.2) sledge
- 2 D A: the sledge excellent so what did that generate then? ((write: sledge))
- 3 Bs J: well the sledge manages to keep level by having quite a wide base
- 4 D A: ((write: wide base))
- 5 Bs J: and then a main force in the middle so
- 6 S J: unlike the set of skis
- 7 S J: where quite narrow and
- 8 Bs J: you go up on an edge- when you're turning
- 9 S J: the sledge is er quite broad
- 10 Bs J: and then you have the weight right in the middle
- 11 Bs J: so they manage to keep both runners on the snow-
- 12 D A: ((write: force in middle))
- 13 Be J: more often than say a sledge or a snowboard- a skis or snowboard
- 14 S A: some some guiders almost down the side of this
- 15 Be J: well I guess the easiest way to keep the pen at a right angle would be
- 16 S J: to have a set of stabilisers on it based on the idea of a sledge
- 17 S A: yeah no problem (.) stabilisers (6) like a bicycle yeah that's a good
- 18 D A: ((write: stabilizer))

entropy

$$H = p_1 * h(p_1) + p_2 * h(p_2) + \dots + p_N * h(p_N) \quad (1)$$

p_1, \dots, p_N are probabilities corresponding to N states and $h(p)$ is the information-generating function devised by Shannon which he derived to be $-\log_b(p)$.

Therefore

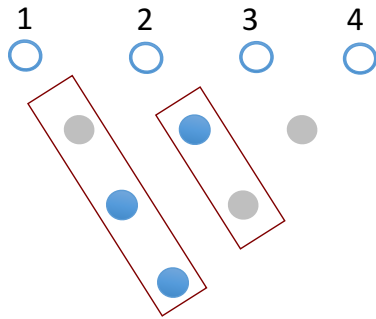
$$H = - \sum_{i=1}^n p_i \log_b(p_i) \quad \text{with} \quad \sum_{i=1}^n p_i = 1 \quad (2)$$

Entropy is calculated according to the probability of ON/OFF of each link. Following Shannon's theory, formula (2), H becomes:

$$-p(\text{ON})\log(p(\text{ON})) - p(\text{OFF})\log(p(\text{OFF})) \quad (3)$$

Assuming that moves / segments in a linkograph are the manifestation of ideas and **entropy** indicates the idea development potential

Types of links

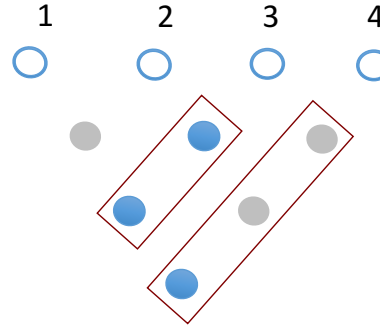


forelinks

links of **moves that connect subsequent moves**;

1 is forelinked to 3 and 4;
forelinks bear evidence to its contribution to the production of further moves.

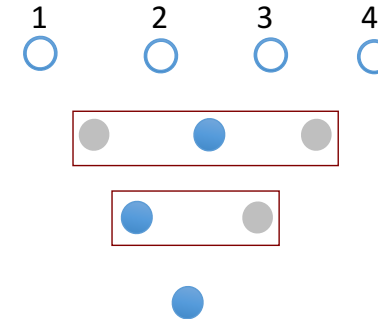
forelink entropy measures idea generation opportunities in terms of new creations or initiations



backlinks

links of **moves that connect to previous moves**; move 4 and 3 are backlinked to 1;
- record the path that led to a move's generation.

backlink entropy measures the opportunities according to responses; opportunity in building upon previous design moves

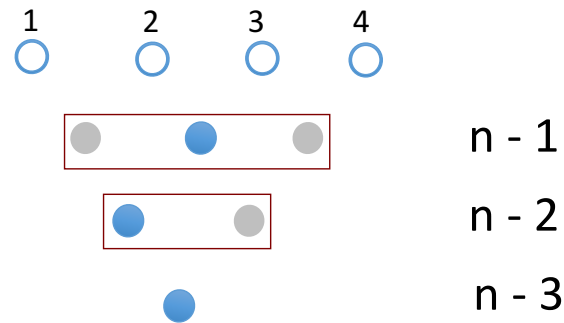


horizonlinks

Link distance -
measure of move-time (separation) between links

Horizonlink entropy measures opportunities relating to cohesiveness and incubation of ideas

horizonlinks

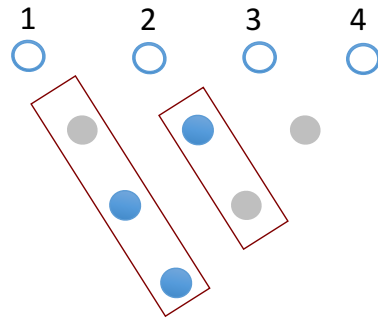


Horizonlink is not a link itself but it bears the notion of length of the links which is a measure of move-time (separation) between links. We can view it as a measure of the distances of the links.

In Figure we can observe there can be $n - 1$ rows in an n moves linkograph.

Let $n - i$ denotes the row number, the links in rows with a small i indicate that the distance between moves is small, we label them as short links. These moves will likely reside in working memory and we refer this to the cohesiveness of ideas. However, if the ideas are too cohesive, it might imply fixation and lack of innovation. The links in the rows with a large i connect moves that are far apart; we call them long links. These moves may not be in the working memory, we consider those as incubated moves. Long links are comparatively rare and may signify reflection in action. Our assumption of a good design process contains unsaturated short links plus a number of long links.

calculating the forelink entropy of an individual segment



forelinks

In segment 1 there are three nodes for links inside the rectangle;

Segments 1 and 2 are unlinked;

segment 1 is linked to segments 3 and 4.

The percentage of linked nodes is 66.6%, and the percentage of unlinked nodes is 33.3%.

If we consider linked nodes as ON and unlinked nodes as OFF, the respective probabilities will be $p(\text{ON}) = 0,666$ and $p(\text{OFF}) = 0,333$.

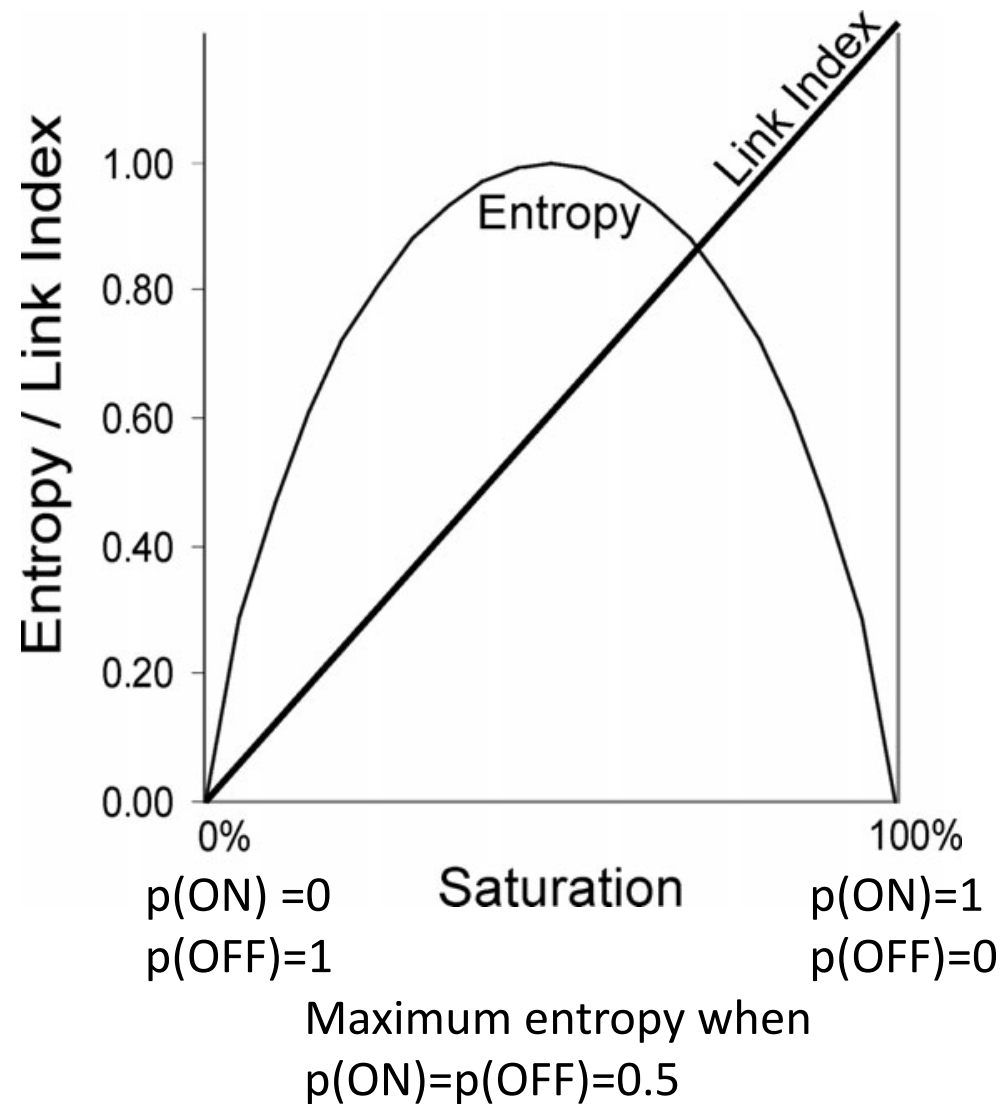
forelink entropy for segment 1:

$$H = 0,666 \log_2(0,666) - 0,333 \log_2(0,33) = 0,918$$


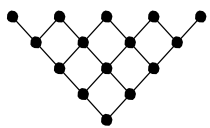
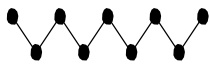
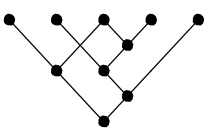
Similarly, for segment 2 the forelink

$$H = 0,5 \log_2(0,5) - 0,5 \log_2(0,5) = 1$$

comparison of the link index and entropy measurement



Some possible linkographs of 5 design moves and their interpretations

			Link Index	Cumulative entropy
Case 1		Five moves are totally unrelated, indicating no converging ideas, very low opportunity for idea development.	0	0
Case 2		All moves are interconnected; this shows that this is a totally integrated process with no diversification, hinting that a premature crystallization or fixation of one idea may have occurred, therefore there is a very low opportunity for novel idea.	2	0
Case 3		Moves are related only to directly preceding moves. This indicates the process is progressing but not developing; indicating some opportunities for idea development.	0,8	5,46
Case 4		Moves are inter-related but not totally connected, indicating that there are lots of opportunities for good ideas with development.	1	8,56

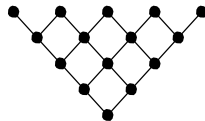
Some possible linkographs of 5 design moves and their interpretations

Case 1



	Forelink Entropy				
	Move 1	Move 2	Move 3	Move 4	Total
Case 1	0	0	0	0	0
Case 2	0	0	0	0	0
Case 3	0.811	0.918	1.000	0	2.730
Case 4	1.000	0.918	1.000	0	2.918

Case 2

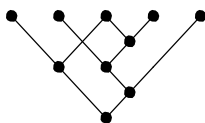


	Backlink Entropy				
	Move 2	Move 3	Move 4	Move 5	Total
Case 1	0	0	0	0	0
Case 2	0	0	0	0	0
Case 3	0	1.000	0.918	0.811	2.730
Case 4	0	1.000	0.918	1.000	2.918

Case 3



Case 4



	Horizonlink Entropy			
	n-1	n-2	n-3	Total
Case 1	0	0	0	0
Case 2	0	0	0	0
Case 3	0	0	0	0
Case 4	0.811	0.918	1.000	2.730

Cumulative entropy
of each case

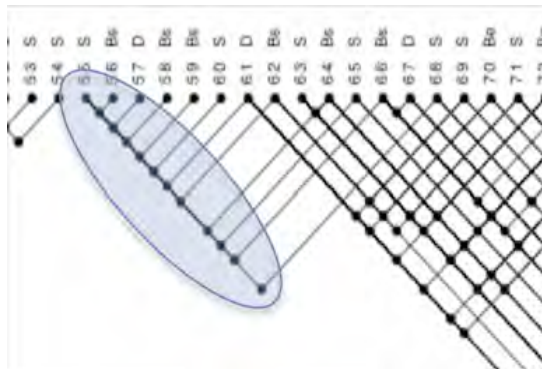
Case 1	Case 2	Case 3	Case 4
0	0	5.459	8.566

Fixation, functional fixedness

Assuming that moves / segments in a linkograph are the manifestation of ideas and entropy indicates the idea development potential.

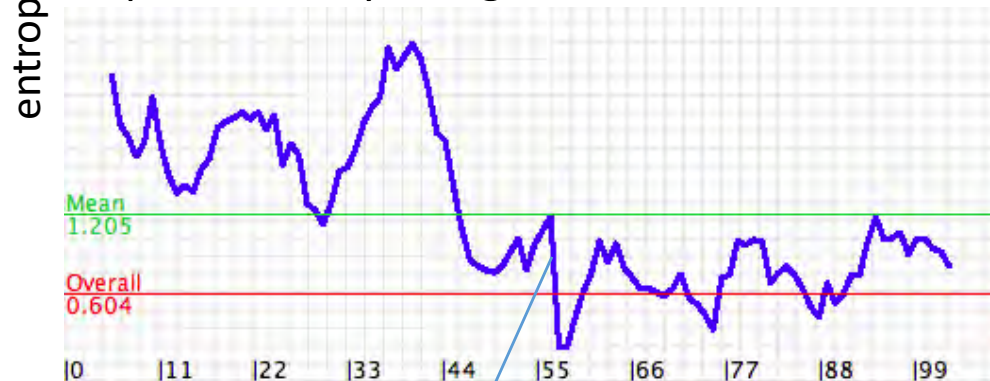
Manifest in linkograph as heavy linking from later design issues to a single or small group of earlier design issues...

results in a sharp drop in info content (entropy) of the design activity as it now focuses on a single or a small number of issues.



Subset of linkograph showing where fixation is located

dynamic entropy of the linkograph produced by using a window of width 12



fixation causes a sharp drop in entropy

Dynamic Models

information about changes that occur during any design session.

In order to capture the dynamic nature of designing, LINKODERer treats the coded protocols using three additional approaches:

1. fractioning
2. trimming
3. windowing

1. **fractioning**: the input dataset is divided into sections and each section is treated individually. The resulting measurements account for the situation at the related fraction of the protocol, e.g., the beginning of the design session.

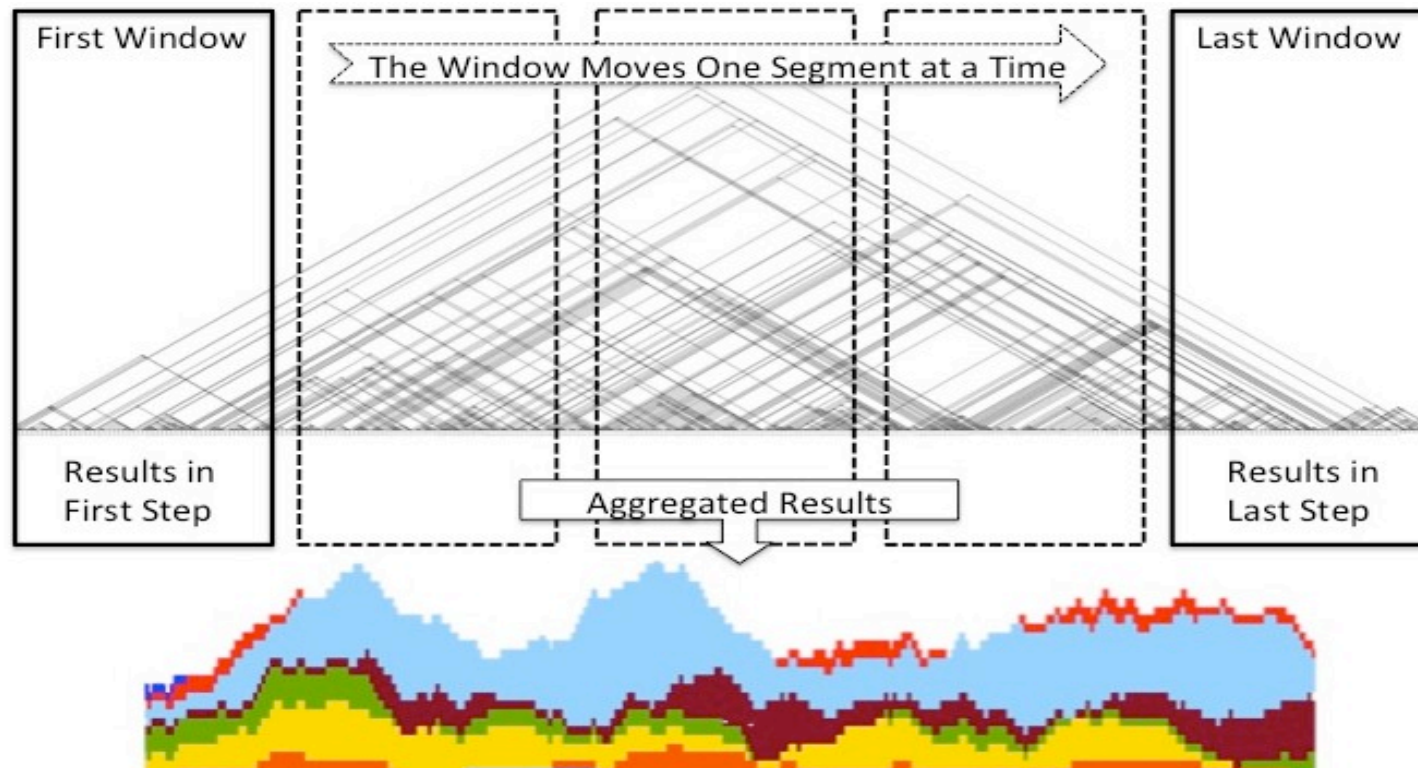
Comparisons are possible between the fractions of a single case or similar fractions from multiple cases.

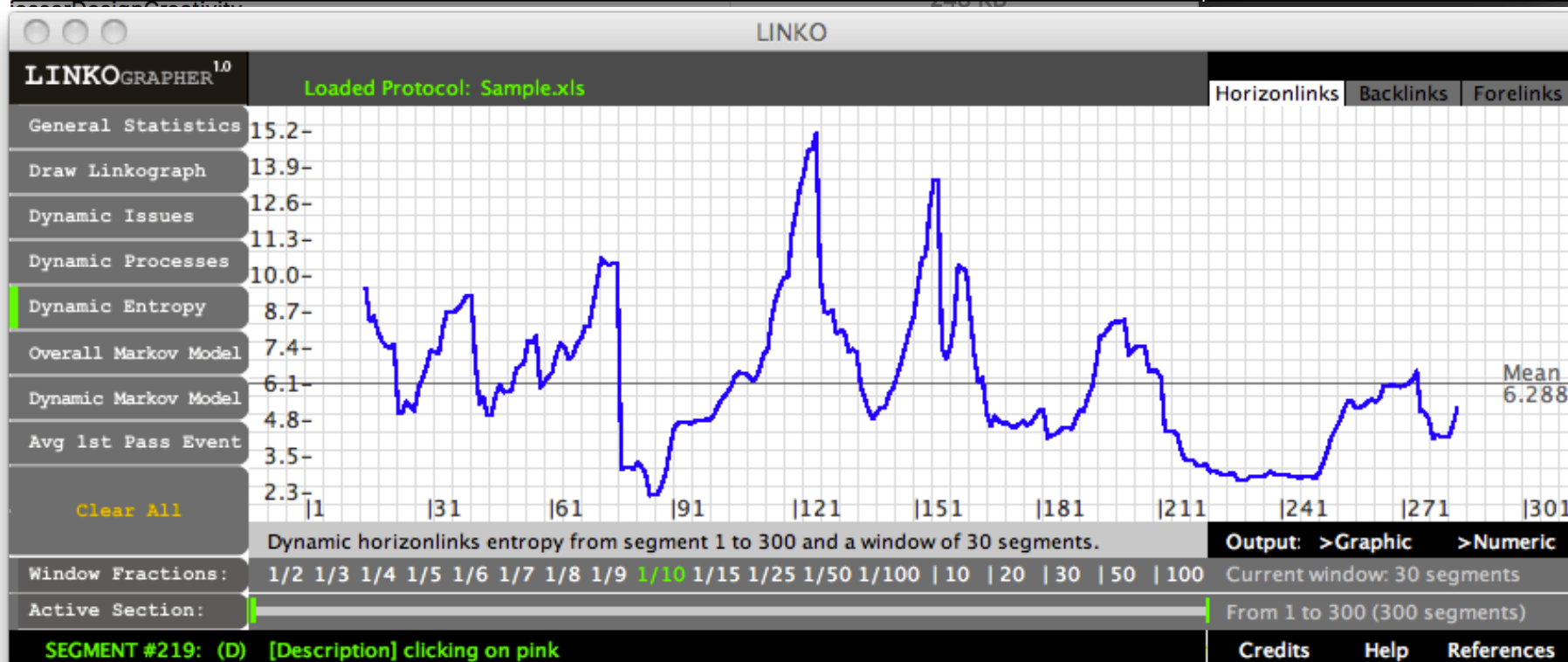
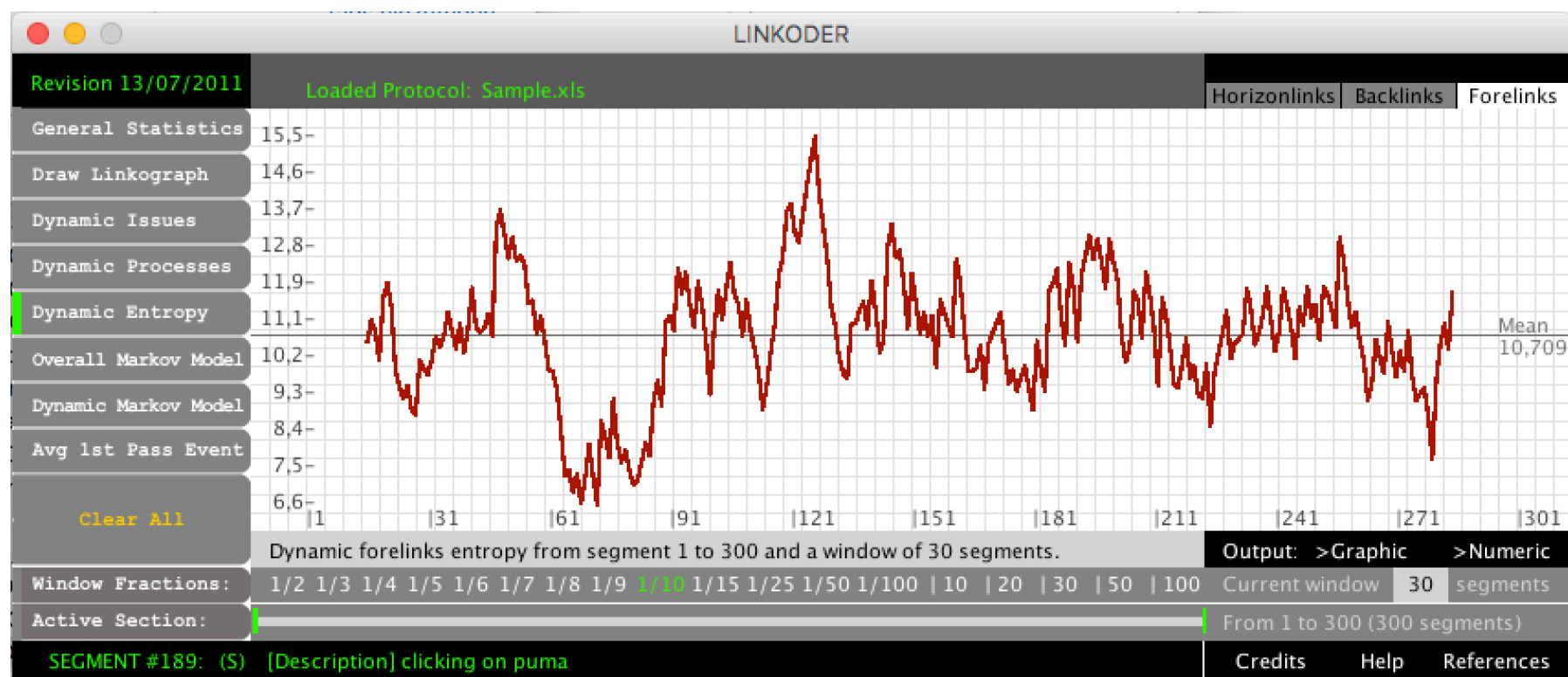
2. **trimming** is the process of selecting a set of contiguous events and excluding all events preceding and following that set. This allows for analyses of a subset of the protocol by itself.

3. Windowing: a fixed number of segments are selected and the analyses carried out for those as a window.

The window then is moved from the beginning to the end of the protocol, one segment at a time. Aggregating the results gives an overall insight into the dynamism of the design session for each.

allows for regulating the results of protocol studies to generate equally sized datasets; eg.: if dataset A has 1000 and B has 1200 segments, performing an analysis with window sizes of 100 for A and 120 for B will generate similarly sized results; makes direct comparison possible.





Markov Models

1st order Markov model: the next state of the system only depends on its current state;
to predict the probability of design issues coming after each other in strict time-order sequence (6 x 6 matrix)

2nd order Markov model: not only the current state but also its previous state affects the next state of the system. In FBS coding scheme, the move from a previous state to a current state is considered a design process.

the 2nd order Markov model of a coded protocol describes the probability of a particular design issue following a particular design process (8 x 6 matrix in Linko).

Markov Models

first order Markov model: the next state of the system only depends on its current state;

to predict the probability of design issues coming after each other in strict time-order sequence (6 x 6 matrix)

Syntactic and Semantic 1st order Markov models from segment

		Syntactic					
		R	F	Be	Bs	S	D
Current state	R	?	?	?	?	?	?
	F	?	?	?	?	?	?
	Be	0,00	0,00	0,00	0,00	1,00	0,00
	Bs	0,00	0,00	0,00	0,20	0,40	0,40
	S	0,00	0,00	0,14	0,29	0,29	0,29
	D	0,00	0,00	0,33	0,67	0,00	0,00
		probability for next state					

Extract: engineering design meeting1

Bs. P (S > D)

Linkograh:

18 segments

7 (S > ...) transitions

2 (S > D) transitions

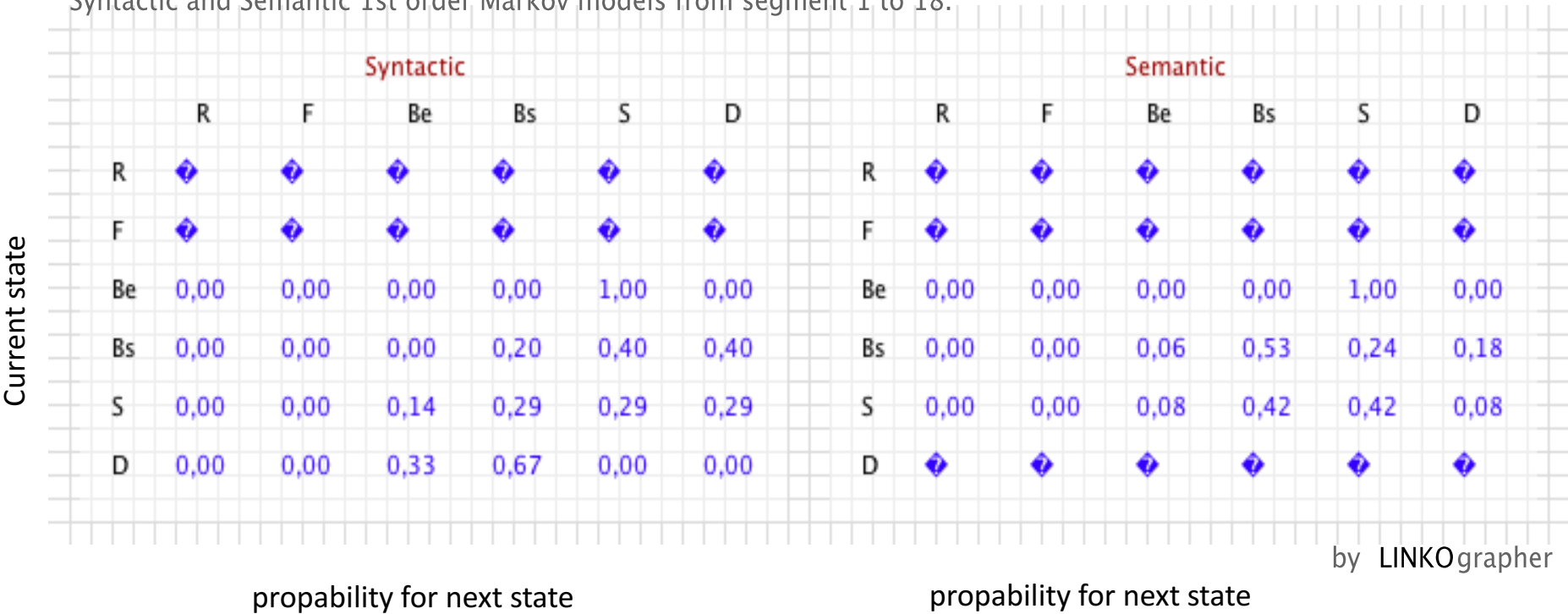
Übergangswahrscheinlichkeit

$$P_{(S>D)} = 2/7 = 0,29$$

Markov Models

Extract: engineering design meeting1

Syntactic and Semantic 1st order Markov models from segment 1 to 18.



LINKO

LINKO^{1.0}GRAPHER

Loaded Protocol: Sample.xls

1st Order2nd Order

General Statistics

Draw Linkograph

Dynamic Issues

Dynamic Processes

Dynamic Entropy

Overall Markov Model

Dynamic Markov Model

Avg 1st Pass Event

Clear All

		Syntactic							Semantic					
		R	F	Be	Bs	S	D		R	F	Be	Bs	S	D
R		0.00	0.12	0.25	0.25	0.25	0.12	R	0.16	0.02	0.21	0.09	0.49	0.02
F		0.00	0.00	0.25	0.25	0.50	0.00	F	0.00	0.29	0.14	0.29	0.29	0.00
Be		0.03	0.03	0.33	0.25	0.33	0.03	Be	0.06	0.03	0.42	0.23	0.25	0.02
Bs		0.04	0.01	0.12	0.22	0.56	0.04	Bs	0.06	0.00	0.18	0.42	0.31	0.02
S		0.02	0.01	0.05	0.22	0.51	0.19	S	0.02	0.00	0.08	0.23	0.52	0.14
D		0.03	0.00	0.12	0.39	0.45	0.00	D	0.08	0.00	0.15	0.38	0.35	0.04

Syntactic and Semantic 1st order Markov models from segment 1 to 300.

Output: >Graphic >Numeric

Window Fractions: 1/2 1/3 1/4 1/5 1/6 1/7 1/8 1/9 1/10 1/15 1/25 1/50 1/100 | 10 | 20 | 30 | 50 | 100

Current window: 30 segments

Active Section:

From 1 to 300 (300 segments)

SEGMENT #219: (D) [Description] clicking on pink

CreditsHelpReferences

first order Markov Transition Matrix

engineering design meeting1, Brain Storming session

	R	F	Be	Bs	S	D
R	0.50	0	0	0	0.50	0
F	0	0.26	0.47	0.04	0.23	0
Be	0	0.07	0.33	0.18	0.38	0.05
Bs	0	0.01	0.20	0.40	0.34	0.05
S	0	0.03	0.14	0.30	0.45	0.08
D	0	0.01	0.14	0.21	0.59	0.05

Study: Software Design Cognition

2 software designers;

their task was to design a traffic flow simulation program.

Overall Markov 1stOrder syntactic

$P =$

	R	F	Be	Bs	S	D
R	0,29	0,00	0,12	0,00	0,41	0,18
F	0,00	0,00	0,67	0,00	0,00	0,33
Be	0,00	0,01	0,21	0,23	0,39	0,16
Bs	0,02	0,00	0,47	0,15	0,29	0,07
S	0,03	0,01	0,26	0,20	0,19	0,31
D	0,01	0,00	0,42	0,15	0,43	0,01

probability matrix P describes the transition of the six FBS states (R, F, Be, Bs, S and D)

Study: Software Design Cognition

2 software designers

1st Order Markov syntactic

P1, P2, P3 are the probability transition matrices of the 3 fractions of the session

$$P_1 = \begin{pmatrix} & R & F & Be & Bs & S & D \\ R & 0.33 & 0.00 & 0.13 & 0.00 & 0.33 & 0.20 \\ F & 0.00 & 0.00 & 0.67 & 0.00 & 0.00 & 0.33 \\ Be & 0.00 & 0.02 & 0.09 & 0.16 & 0.42 & 0.30 \\ Bs & 0.04 & 0.00 & 0.40 & 0.16 & 0.28 & 0.12 \\ S & 0.07 & 0.04 & 0.16 & 0.14 & 0.16 & 0.44 \\ D & 0.03 & 0.00 & 0.40 & 0.18 & 0.43 & 0.00 \end{pmatrix}$$

$$P_2 = \begin{pmatrix} & R & F & Be & Bs & S & D \\ R & 0.00 & 0.00 & 0.00 & 0.00 & 1.00 & 0.00 \\ F & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 \\ Be & 0.00 & 0.00 & 0.26 & 0.08 & 0.49 & 0.17 \\ Bs & 0.00 & 0.00 & 0.40 & 0.23 & 0.34 & 0.03 \\ S & 0.01 & 0.00 & 0.26 & 0.24 & 0.23 & 0.26 \\ D & 0.00 & 0.00 & 0.37 & 0.17 & 0.43 & 0.03 \end{pmatrix}$$

$$P_3 = \begin{pmatrix} & R & F & Be & Bs & S & D \\ R & 0.00 & 0.00 & 0.00 & 0.00 & 1.00 & 0.00 \\ F & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 & 0.00 \\ Be & 0.00 & 0.00 & 0.24 & 0.39 & 0.31 & 0.07 \\ Bs & 0.02 & 0.00 & 0.57 & 0.09 & 0.25 & 0.07 \\ S & 0.00 & 0.00 & 0.38 & 0.21 & 0.17 & 0.23 \\ D & 0.00 & 0.00 & 0.53 & 0.05 & 0.42 & 0.00 \end{pmatrix}$$

Markov Models

average first pass event model

determines **how many states it takes to transit from one specific state to another**

how many segments the designer needs to move from one design issue to another one.
(6 x 6 matrix)

The mean first passage times matrix can be used to validate hypotheses such as design processes take longer to get from function – intention (F) to structure – a design proposal (S) than from behavior (B) to structure (S).

LINKO

LINKO^{1.0}GRAPHER

Loaded Protocol: Sample.xls

Overall

General Statistics

Draw Linkograph

Dynamic Issues

Dynamic Processes

Dynamic Entropy

Overall Markov Model

Dynamic Markov Model

Avg 1st Pass Event

Clear All

Average First Passage Events Matrix

	R	F	Be	Bs	S	D
R	7.24	15.54	1.58	1.79	1.08	2.88
F	3.56	20.33	3.33	0.67	0.67	2.17
Be	4.72	13.67	2.66	1.27	0.92	3.24
Bs	6.17	15.70	2.87	1.38	0.66	3.67
S	6.03	13.76	3.15	1.47	0.67	2.53
D	3.64	11.11	2.59	1.11	0.75	2.97

Shortest Passage Events

	Bs -> S
F -> Bs	0.67
F -> S	0.67
S -> S	0.67
D -> S	0.75
Be -> S	0.92
...	

Longest Passage Events

	F -> F
Bs -> F	20.33
R -> F	15.54
S -> F	13.76
Be -> F	13.67
D -> F	11.11
...	

Normalised First Passage Event from segment 1 to 300.

Output: >Graphic >Numeric

Window Fractions:

1/2 1/3 1/4 1/5 1/6 1/7 1/8 1/9 1/10 1/15 1/25 1/50 1/100 | 10 | 20 | 30 | 50 | 100

Current window: 30 segments

Active Section:

From 1 to 300 (300 segments)

SEGMENT #284: (S) Tongue lining.

Credits

Help

References

Markov Models

average first pass event model

	R	F	Be	Bs	S	D
R	$m_{1,1}$	$m_{1,2}$	$m_{1,3}$	$m_{1,4}$	$m_{1,5}$	$m_{1,6}$
F	$m_{2,1}$	$m_{2,2}$	$m_{2,3}$	$m_{2,4}$	$m_{2,5}$	$m_{2,6}$
Be	$m_{3,1}$	$m_{3,2}$	$m_{3,3}$	$m_{3,4}$	$m_{3,5}$	$m_{3,6}$
Bs	$m_{4,1}$	$m_{4,2}$	$m_{4,3}$	$m_{4,4}$	$m_{4,5}$	$P_{4,6}$
S	$m_{5,1}$	$m_{5,2}$	$m_{5,3}$	$m_{5,4}$	$m_{5,5}$	$m_{5,6}$
D	$m_{6,1}$	$m_{6,2}$	$m_{6,3}$	$m_{6,4}$	$m_{6,5}$	$m_{6,6}$

m_{ij} ... average number of steps required to get from one state to another

Markov Models

average first passage

engineering design meeting1, Brain Storming session

$$M_{bs} =$$

	<i>R</i>	<i>F</i>	<i>Be</i>	<i>Bs</i>	<i>S</i>	<i>D</i>
<i>R</i>	$\approx \infty$	35.91	7.66	5.77	2.38	18.72
<i>F</i>	$\approx \infty$	25.13	3.26	5.30	3.57	18.52
<i>Be</i>	$\approx \infty$	32.12	4.49	4.42	3.07	17.40
<i>Bs</i>	$\approx \infty$	34.36	5.34	3.39	3.16	17.32
<i>S</i>	$\approx \infty$	33.91	5.66	3.77	2.85	16.72
<i>D</i>	$\approx \infty$	34.30	5.75	4.11	2.48	17.05

Markov Models

average first passage

2 software designers. Their task was to design a traffic flow simulation program.

	R	F	Be	Bs	S	D
R	49,1	168,4	3,9	6,7	2,5	5,0
F	70,0	168,4	1,9	6,2	3,7	4,5
Be	69,3	167,3	3,2	5,0	2,7	5,3
Bs	68,3	168,2	2,5	5,4	2,9	5,8
S	67,6	166,7	3,1	5,2	3,2	4,6
D	68,6	168,1	2,7	5,4	2,6	6,0

Markov Models average first passage

transition matrices
of the **3 fractions of
the session**

2 software designers. Their
task was to design a traffic
flow simulation program.

Kan & Gero (2010). Using
a Generic Method to
Study Software Design
Cognition

	R	F	Be	Bs	S	D
R	20,1	61,6	4,4	8,3	2,8	3,6
F	30,4	61,3	2,1	7,7	3,6	3,1
Be	29,6	60,0	4,1	6,7	2,6	3,2
Bs	28,8	61,3	3,1	6,8	2,9	3,8
S	27,9	59,6	3,8	6,9	3,3	2,8
D	29,1	61,1	3,2	6,7	2,6	4,2

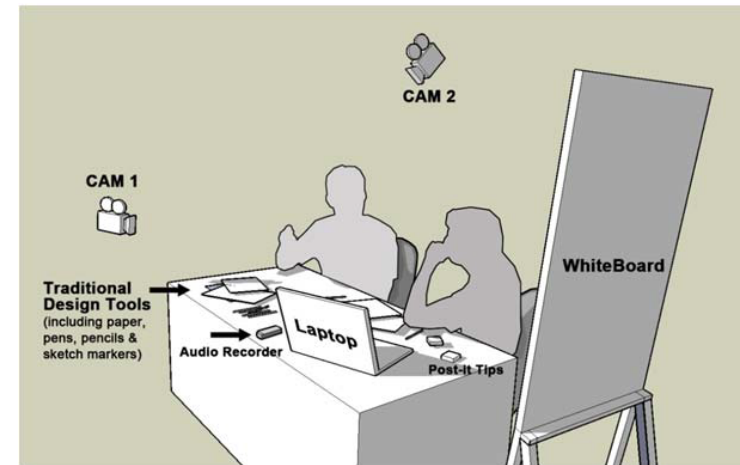
	R	F	Be	Bs	S	D
R	192,8	∞	4,3	6,6	1,0	6,4
F	194,2	∞	4,2	6,9	3,4	6,8
Be	193,9	∞	3,3	6,4	2,1	5,6
Bs	194,3	∞	2,9	5,6	2,5	6,6
S	191,8	∞	3,3	5,6	2,8	5,4
D	194,1	∞	3,0	6,0	2,3	6,5

	R	F	Be	Bs	S	D
R	188,8	∞	3,3	5,0	1,0	8,8
F	187,7	∞	3,3	4,8	4,4	9,8
Be	187,1	∞	2,6	3,3	3,3	9,1
Bs	183,8	∞	2,0	4,3	3,4	9,2
S	187,8	∞	2,3	4,0	3,7	7,8
D	188,2	∞	2,1	4,4	2,9	9,6

(Vergleichs-) Studien

The assignments for experiment were conceptual design under two different situations.

- 1) to design a coffee maker for an existing market (Task CM), which was treated as a variant or adaptive design task
- 2) a visionary concept design, to design a next-generation personal entertainment system/ device for the year 2025 (Task PES).



Experiment Setup (Jiang & Yen, 2010)

Four teams of final-year Industrial Design (ID) students participated in this study voluntarily. Their average age was 23 years old.

Frequency distribution of design issues for Industrial Design Student-teams working on different tasks

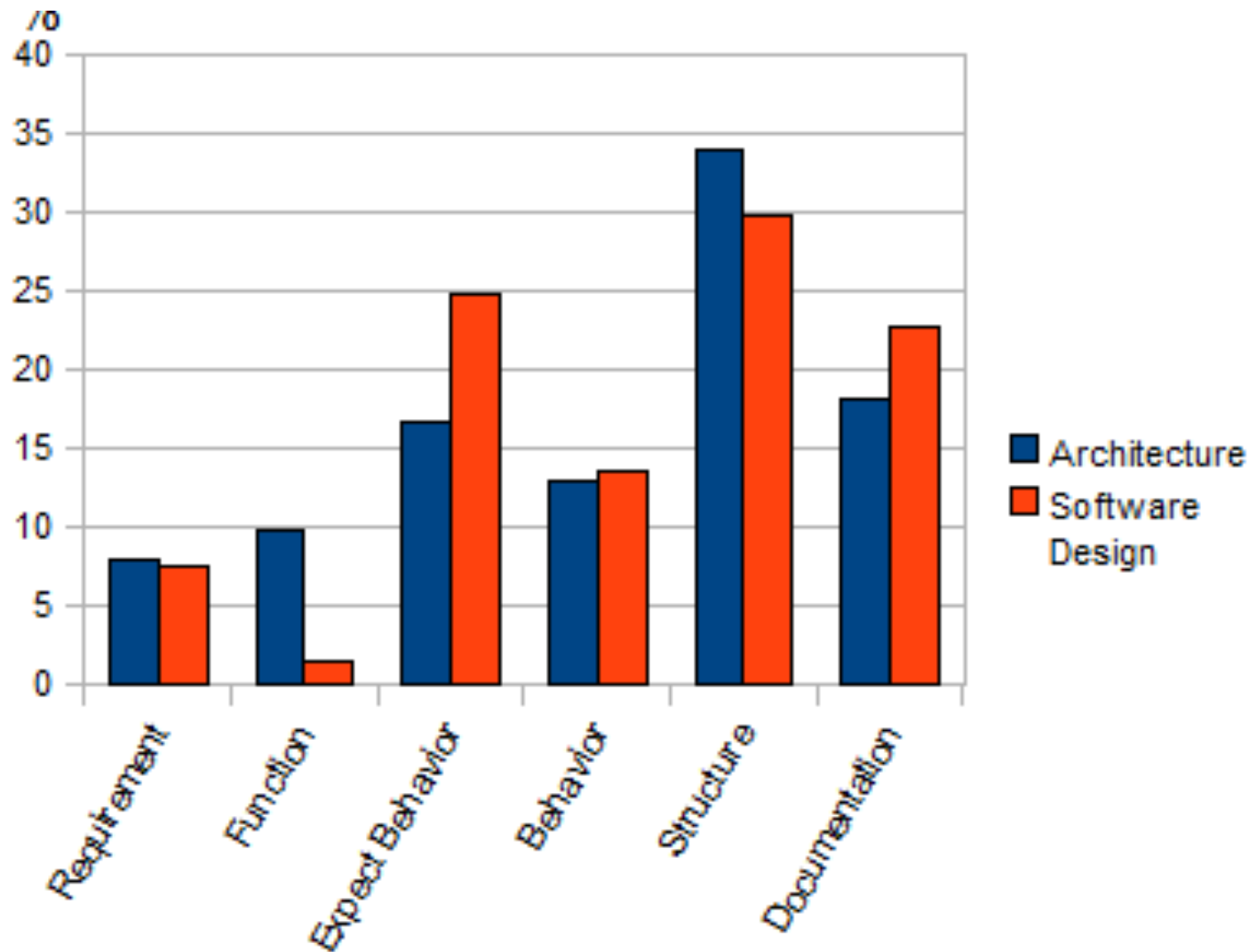
adaptive design task: Coffee Machine (CM)

Team	R (%)	F (%)	Be (%)	Bs (%)	S (%)	D (%)
ID1	1.9	28.0	22.7	13.6	12.2	21.5
ID2	0.5	33.4	19.7	14.0	9.1	1.9
ID3	1.8	24.9	26.9	16.3	14.5	15.5
ID4	1.6	25.5	22.9	18.9	16.8	14.3

visionary concept design (PES task)

	R (%)	F (%)	Be (%)	Bs (%)	S (%)	D (%)
ID1	0.9	22.1	12.7	17.0	22.5	24.8
ID2	0.4	26.1	11.4	19.0	18.5	24.6
ID3	1.3	25.9	18.5	20.8	19.7	13.9
ID4	0.8	20.4	19.7	25.9	20.6	12.5

Comparison between architects and software designers of the distributions of design processes



Comparison between architects and software designers of the distributions of design processes

