

# Kronecker Algebra

Computer Systems

Johann Blieberger

1 **Kronecker Product**

2 **Verifying Programs**

3 **The Kronecker Sum**

# Kronecker Product

# Kronecker Product of Finite State Machines (FSMs)

## Definition

Given an  $m$ -by- $n$  matrix  $A$  and a  $p$ -by- $q$  matrix  $B$ , their Kronecker product denoted by  $A \otimes B$  is a  $mp$ -by- $nq$  block matrix defined by

$$A \otimes B = \begin{pmatrix} a_{1,1}B & \dots & a_{1,n}B \\ \vdots & \ddots & \vdots \\ a_{m,1}B & \dots & a_{m,n}B \end{pmatrix}.$$

# Kronecker Product

## Example

For example, if

$$A = \begin{pmatrix} a_{1,1} & a_{1,2} \\ a_{2,1} & a_{2,2} \end{pmatrix}$$

and

$$B = \begin{pmatrix} b_{1,1} & b_{1,2} & b_{1,3} \\ b_{2,1} & b_{2,2} & b_{2,3} \\ b_{3,1} & b_{3,2} & b_{3,3} \end{pmatrix},$$

then

$$A \otimes B = \begin{pmatrix} a_{1,1}b_{1,1} & a_{1,1}b_{1,2} & a_{1,1}b_{1,3} & a_{1,2}b_{1,1} & a_{1,2}b_{1,2} & a_{1,2}b_{1,3} \\ a_{1,1}b_{2,1} & a_{1,1}b_{2,2} & a_{1,1}b_{2,3} & a_{1,2}b_{2,1} & a_{1,2}b_{2,2} & a_{1,2}b_{2,3} \\ a_{1,1}b_{3,1} & a_{1,1}b_{3,2} & a_{1,1}b_{3,3} & a_{1,2}b_{3,1} & a_{1,2}b_{3,2} & a_{1,2}b_{3,3} \\ a_{2,1}b_{1,1} & a_{2,1}b_{1,2} & a_{2,1}b_{1,3} & a_{2,2}b_{1,1} & a_{2,2}b_{1,2} & a_{2,2}b_{1,3} \\ a_{2,1}b_{2,1} & a_{2,1}b_{2,2} & a_{2,1}b_{2,3} & a_{2,2}b_{2,1} & a_{2,2}b_{2,2} & a_{2,2}b_{2,3} \\ a_{2,1}b_{3,1} & a_{2,1}b_{3,2} & a_{2,1}b_{3,3} & a_{2,2}b_{3,1} & a_{2,2}b_{3,2} & a_{2,2}b_{3,3} \end{pmatrix}.$$

# Kronecker Product

---

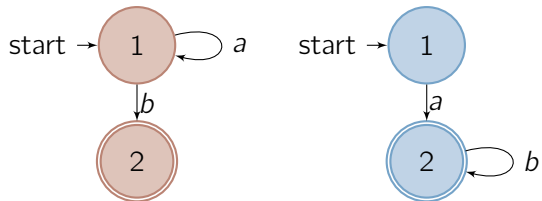


Abbildung: FSMs *A* (left) and *B* (right)

# Kronecker Product

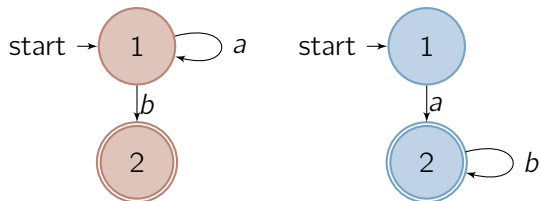


Abbildung: FSMs  $A$  (left) and  $B$  (right)

## Example

matrices

$$A = \begin{pmatrix} a & b \\ 0 & 0 \end{pmatrix}, B = \begin{pmatrix} 0 & a \\ 0 & b \end{pmatrix}, A \otimes B = \begin{pmatrix} \cdot & aa & \cdot & ba \\ \cdot & ab & \cdot & bb \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

# Kronecker Product

## Initial and Final States

Let  $S_A$  and  $S_B$  be the initial state vectors of the operands,  $F_A$  and  $F_B$  their final state vectors. Then the initial vector of the Kronecker product is given by  $S_A \otimes S_B$  and its final vector is  $F_A \otimes F_B$ .

## Example

$S_A = (1, 0)$ ,  $S_B = (1, 0)$ ,  $F_A = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ , and  $F_B = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ . Thus  $S_{A \otimes B} = (1, 0, 0, 0)$  and

$$F_{A \otimes B} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

which simply state that the initial state of the Kronecker product FSM  $A \otimes B$  is state 1 and its final state is state 4.



# Kronecker Product for FSMs

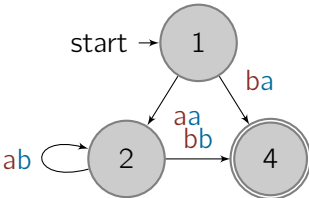


Abbildung: Graphical Representation of  $A \otimes B$

# Kronecker Product for FSMs

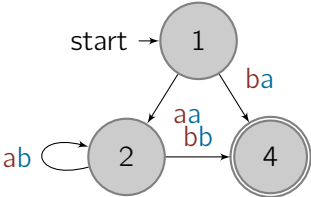


Abbildung: Graphical Representation of  $A \otimes B$

## Surprise

matrix has size four

# Kronecker Product for FSMs

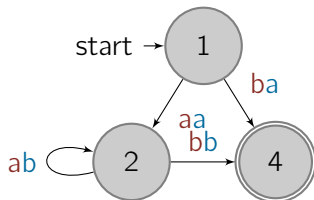


Abbildung: Graphical Representation of  $A \otimes B$

## Surprise

matrix has size four  
only three states above

# Kronecker Product for FSMs

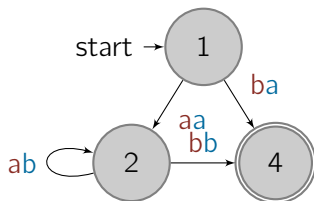


Abbildung: Graphical Representation of  $A \otimes B$

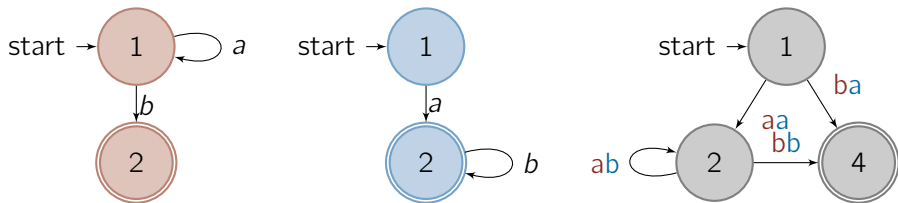
## Surprise

matrix has size four

only three states above

State 3 cannot be reached from the initial state 1!

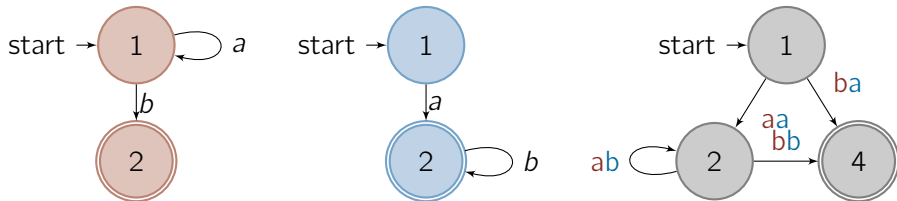
# Kronecker Product for FSMs



Both FSMs, *A* and *B* perform their state transitions in *lockstep*.

- At the beginning, both FSMs are in their initial state. *B* has to proceed to state 2, thereby generating output *a*. *A* has two possible successor states:
  - A* stays in state 1, producing output *a*. This corresponds to state transition  $1 \rightarrow 2$  in the product FSM.
  - A* proceeds to its state 2 (output: *b*). This corresponds to state transition  $1 \rightarrow 4$  in the product FSM.

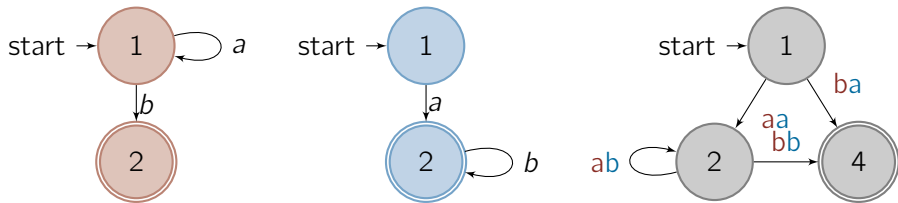
# Kronecker Product for FSMs



Both FSMs,  $A$  and  $B$  perform their state transitions in *lockstep*.

- 2 If the previous step was 1A, both FSMs can now produce together an arbitrary number of  $ab$ -pairs. This corresponds to the transition  $2 \rightarrow 2$  in the product FSM. When  $A$  issues a  $b$ ,  $B$  also has to produce a  $b$ . This corresponds to transition  $2 \rightarrow 4$  in the product FSM. Then both FSMs are in their final states.  $A$  cannot do a further state transition and both FSMs and the product FSM terminate.

# Kronecker Product for FSMs



Both FSMs, *A* and *B* perform their state transitions in *lockstep*.

- 3 If the previous step was 1B, both FSMs are in their final states. Since *A* cannot proceed, both FSMs and the product FSM terminate.

# Kronecker Product for FSMs

---

## Theorem

*Given two FSMs A and B, their Kronecker product FSM generates the same output than A and B do when they execute in lockstep.*



# Kronecker Product for FSMs

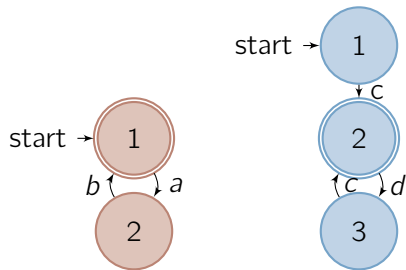


Abbildung: FSMs *C* (left) and *D* (right)

# Kronecker Product for FSMs

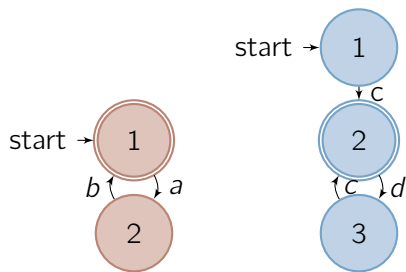


Abbildung: FSMs  $C$  (left) and  $D$  (right)

$C$  terminates only when it has done an even number of state transitions

# Kronecker Product for FSMs

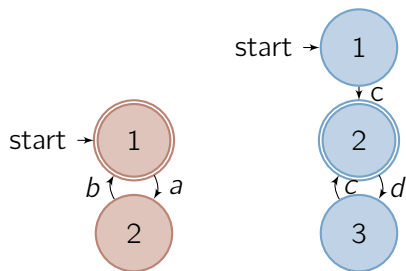


Abbildung: FSMs  $C$  (left) and  $D$  (right)

$C$  terminates only when it has done an even number of state transitions

$D$  can terminate only after it has done an odd number of transitions

# Kronecker Product for FSMs

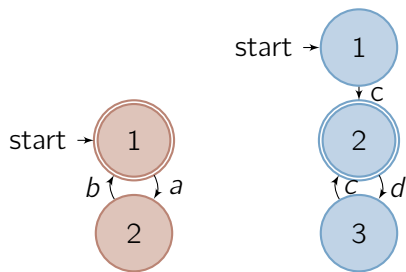


Abbildung: FSMs  $C$  (left) and  $D$  (right)

$C$  terminates only when it has done an even number of state transitions  
 $D$  can terminate only after it has done an odd number of transitions  
overall output of  $C \dots (ab)^*$

# Kronecker Product for FSMs

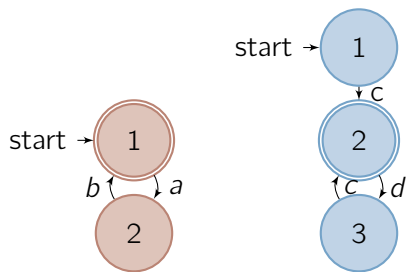


Abbildung: FSMs  $C$  (left) and  $D$  (right)

$C$  terminates only when it has done an even number of state transitions

$D$  can terminate only after it has done an odd number of transitions

overall output of  $C \dots (ab)^*$

overall output of  $D \dots c(dc)^*$

# Kronecker Product for FSMs

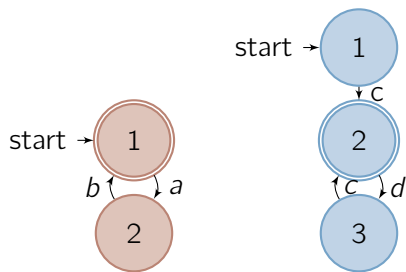


Abbildung: FSMs  $C$  (left) and  $D$  (right)

$C$  terminates only when it has done an even number of state transitions

$D$  can terminate only after it has done an odd number of transitions

overall output of  $C \dots (ab)^*$

overall output of  $D \dots c(dc)^*$

the Kronecker product of  $C$  and  $D \dots$

# Kronecker Product for FSMs

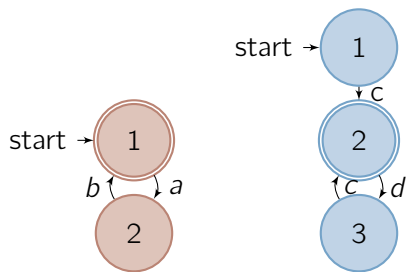


Abbildung: FSMs  $C$  (left) and  $D$  (right)

$C$  terminates only when it has done an even number of state transitions

$D$  can terminate only after it has done an odd number of transitions

overall output of  $C \dots (ab)^*$

overall output of  $D \dots c(dc)^*$

the Kronecker product of  $C$  and  $D \dots 0$ .

# Kronecker Product for FSMs

---

$$C = \begin{pmatrix} \cdot & a \\ b & \cdot \end{pmatrix} \text{ and } D = \begin{pmatrix} \cdot & c & \cdot \\ \cdot & \cdot & d \\ \cdot & c & \cdot \end{pmatrix}$$

$$C \otimes D = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot & ac & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & ad \\ \cdot & \cdot & \cdot & \cdot & ac & \cdot \\ \cdot & bc & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & bd & \cdot & \cdot & \cdot \\ \cdot & bc & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$



# Kronecker Product for FSMs

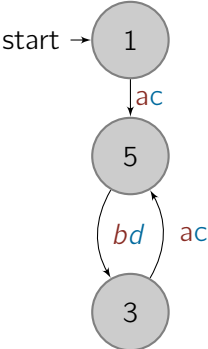


Abbildung: Graphical Representation of  $C \otimes D$

the final state 2

# Kronecker Product for FSMs

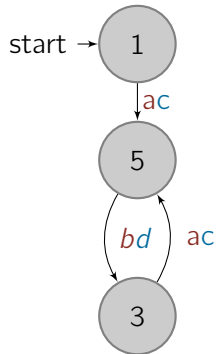


Abbildung: Graphical Representation of  $C \otimes D$

the final state 2  
cannot be reached from the initial state 1.

# Verifying Programs

# Verifying Programs

---

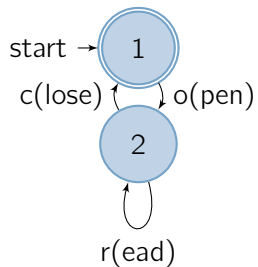


Abbildung: Graphical Representation of File Usage Scenario  $F$

# Verifying Programs

---

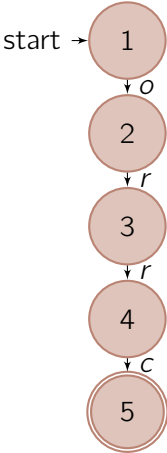


Abbildung: Graphical Representation of File Usage System A

# Verifying Programs

$$A \otimes F = \begin{pmatrix} \cdot & o & \cdot & \cdot & \cdot \\ \cdot & \cdot & r & \cdot & \cdot \\ \cdot & \cdot & \cdot & r & \cdot \\ \cdot & \cdot & \cdot & \cdot & c \\ \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix} \otimes \begin{pmatrix} \cdot & o \\ c & r \end{pmatrix} = \begin{pmatrix} \cdot & \cdot & \cdot & oo & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & oc & or & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & ro & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & rc & rr & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & ro & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & rc & rr & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & co \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & cc & cr \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix} .$$

# Verifying Programs

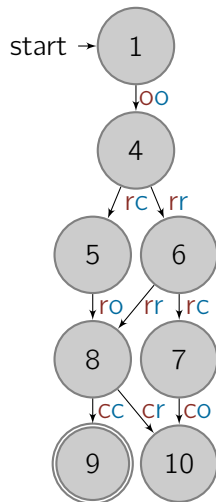


Abbildung: Graphical Representation of  $A \otimes F$

# Verifying Programs

---

pairings  $rc$ ,  $ro$ , ... do not make sense (lockstep!)



# Verifying Programs

---

pairings  $rc$ ,  $ro$ , ... do not make sense (lockstep!)  
we change the definition of the Kronecker product a little bit:

# Verifying Programs

---

pairings  $rc$ ,  $ro$ ,  $\dots$  do not make sense (lockstep!)

we change the definition of the Kronecker product a little bit:

We assume that  $rc = ro = \dots = 0$

# Verifying Programs

---

pairings  $rc$ ,  $ro$ ,  $\dots$  do not make sense (lockstep!)

we change the definition of the Kronecker product a little bit:

We assume that  $rc = ro = \dots = 0$

and for simplicity set  $oo = o$ ,  $rr = r$ , and  $cc = c$ .

# Verifying Programs

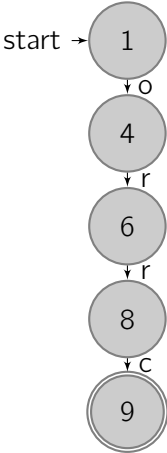


Abbildung: Graphical Representation of "new"  $A \otimes F$

# Verifying Programs

---

Figures are very similar

# Verifying Programs

---

Figures are very similar  
In fact only the node IDs differ

# Verifying Programs

---

Figures are very similar

In fact only the node IDs differ

In graph theory, an *isomorphism* of graphs  $G$  and  $H$  is a bijection  $f$  between the node sets of  $G$  and  $H$  such that any two nodes  $u$  and  $v$  of  $G$  are adjacent in  $G$  if and only if  $f(u)$  and  $f(v)$  are adjacent in  $H$ . If an isomorphism exists between two graphs, then the graphs are called *isomorphic*. We write  $G \simeq H$  in such a case.

# Verifying Programs

---

Figures are very similar

In fact only the node IDs differ

In graph theory, an *isomorphism* of graphs  $G$  and  $H$  is a bijection  $f$  between the node sets of  $G$  and  $H$  such that any two nodes  $u$  and  $v$  of  $G$  are adjacent in  $G$  if and only if  $f(u)$  and  $f(v)$  are adjacent in  $H$ . If an isomorphism exists between two graphs, then the graphs are called *isomorphic*. We write  $G \simeq H$  in such a case.

So, clearly the graphs of our example are isomorphic.



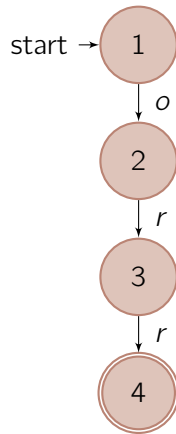


Abbildung: Graphical Representation of File Usage System  $B$

# Verifying Programs

---

$$B = \begin{pmatrix} \cdot & o & \cdot & \cdot \\ \cdot & \cdot & r & \cdot \\ \cdot & \cdot & \cdot & r \\ \cdot & \cdot & \cdot & \cdot \end{pmatrix}, B \otimes F = \begin{pmatrix} \cdot & \cdot & \cdot & o & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & r & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & r \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

# Verifying Programs

---

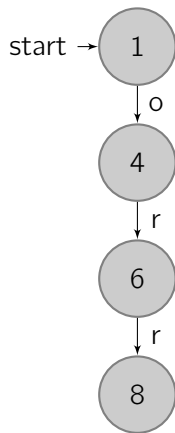


Abbildung: Graphical Representation of  $B \otimes F$

# Verifying Programs

---

Isomorphic?

# Verifying Programs

---

Isomorphic?

## Definition

An isomorphism of two control flow graphs (CFGs)  $G$  and  $H$  is a bijection  $f$  between the node sets of  $G$  and  $H$  such that any two nodes  $u$  and  $v$  of  $G$  are adjacent in  $G$  if and only if  $f(u)$  and  $f(v)$  are adjacent in  $H$ . In addition, let  $r$  be the root node of  $G$ . Then  $f(r)$  has to be the root node of  $H$ . For all final nodes  $s$  of  $G$ ,  $f(s)$  have to be final nodes of  $H$ , and for all final nodes  $t$  of  $H$ ,  $f^{-1}(t)$  have to be final nodes in  $G$ . If an isomorphism exists between two CFGs, then the CFGs are called *isomorphic* which we denote by  $G \simeq H$ .

# Verifying Programs

---

Isomorphic?

## Definition

An isomorphism of two control flow graphs (CFGs)  $G$  and  $H$  is a bijection  $f$  between the node sets of  $G$  and  $H$  such that any two nodes  $u$  and  $v$  of  $G$  are adjacent in  $G$  if and only if  $f(u)$  and  $f(v)$  are adjacent in  $H$ . In addition, let  $r$  be the root node of  $G$ . Then  $f(r)$  has to be the root node of  $H$ . For all final nodes  $s$  of  $G$ ,  $f(s)$  have to be final nodes of  $H$ , and for all final nodes  $t$  of  $H$ ,  $f^{-1}(t)$  have to be final nodes in  $G$ . If an isomorphism exists between two CFGs, then the CFGs are called *isomorphic* which we denote by  $G \simeq H$ .

With this definition we still have  $A \otimes F \simeq A$  but  $B \otimes F \not\simeq B$  because there is no final node in this case.

# Verifying Programs

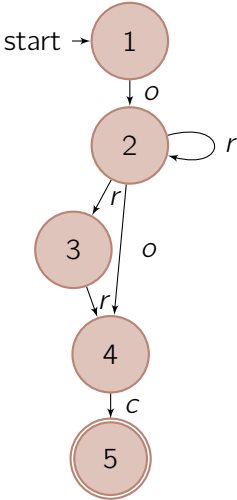


Abbildung: Graphical Representation of File Usage System C

# Verifying Programs

---

$$C \otimes F = \begin{pmatrix} \cdot & o & \cdot & \cdot & \cdot \\ \cdot & r & r & o & \cdot \\ \cdot & \cdot & \cdot & r & \cdot \\ \cdot & \cdot & \cdot & \cdot & c \\ \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix} \otimes \begin{pmatrix} \cdot & o \\ c & r \end{pmatrix} = \begin{pmatrix} \cdot & \cdot & \cdot & o & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & o & \cdot & \cdot \\ \cdot & \cdot & \cdot & r & \cdot & r & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & r & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & c \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$



# Verifying Programs

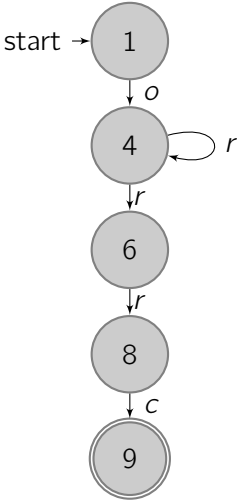


Abbildung: Graphical Representation of  $C \otimes F$

# Verifying Programs

---

Isomorphic?

# Verifying Programs

---

Isomorphic?

General Statement

- 1 Assume we pick a path on program  $P$ 's side, that complies to the usage scenario  $U$ . Then a corresponding path will be present in  $P \otimes U$ .
- 2 Assume we pick a path on program  $P$ 's side, that does not comply completely to the usage scenario  $U$ . Then a “corresponding” path in  $P \otimes U$  will end as soon as the path does not comply to  $U$ . This will result in  $P \not\subseteq P \otimes U$ .

# Verifying Programs

---

Isomorphic?

General Statement

- 1 Assume we pick a path on program  $P$ 's side, that complies to the usage scenario  $U$ . Then a corresponding path will be present in  $P \otimes U$ .
- 2 Assume we pick a path on program  $P$ 's side, that does not comply completely to the usage scenario  $U$ . Then a “corresponding” path in  $P \otimes U$  will end as soon as the path does not comply to  $U$ . This will result in  $P \not\subseteq P \otimes U$ .

Thus we can state:

## Theorem

*Given  $P$ , a control flow graph (CFG) of a program, and a usage scenario  $U$ , program  $P$  complies to  $U$  if and only if  $P \simeq P \otimes U$ .*

# The Kronecker Sum

# The Kronecker Sum

---

- programs will use several objects (classes, modules, packages, ...) for implementing their own task.

# The Kronecker Sum

---

- programs will use several objects (classes, modules, packages, ...) for implementing their own task.
- checking against each of their usage scenarios could be done one after the other.

# The Kronecker Sum

---

- programs will use several objects (classes, modules, packages, ...) for implementing their own task.
- checking against each of their usage scenarios could be done one after the other.
- here: check a program against two and more usage scenarios at the same time.



# The Kronecker Sum

---

- programs will use several objects (classes, modules, packages, ...) for implementing their own task.
- checking against each of their usage scenarios could be done one after the other.
- here: check a program against two and more usage scenarios at the same time.
- Kronecker sum.

# The Kronecker Sum

---

Assume that  $U \in M_n(\mathcal{U})$  and  $W \in M_m(\mathcal{W})$  and that  $\mathcal{U} \cap \mathcal{W} = \emptyset$ .

# The Kronecker Sum

---

Assume that  $U \in M_n(\mathcal{U})$  and  $W \in M_m(\mathcal{W})$  and that  $\mathcal{U} \cap \mathcal{W} = \emptyset$ .  
Introduce self loops on both sides.

# The Kronecker Sum

Assume that  $U \in M_n(\mathcal{U})$  and  $W \in M_m(\mathcal{W})$  and that  $\mathcal{U} \cap \mathcal{W} = \emptyset$ .  
Introduce self loops on both sides.

## Definition

$$U \oplus W = U \otimes \left( W + \left( \sum_{x \in \mathcal{U}} x \right) I_m \right) + \left( U + \left( \sum_{y \in \mathcal{W}} y \right) I_n \right) \otimes W =$$
$$U \otimes W + U \otimes \left( \left( \sum_{x \in \mathcal{U}} x \right) I_m \right) + U \otimes W + \left( \left( \sum_{y \in \mathcal{W}} y \right) I_n \right) \otimes W.$$

Note that  $U \otimes W = Z_{n \cdot m}$  because the edge labels of  $U$  and  $W$  are disjoint. Hence we get

$$U \oplus W = U \otimes I_m + I_n \otimes W.$$

# The Kronecker Sum

---

## Theorem

*With the definitions above, a program  $A$  can be checked against two usage scenarios  $U$  and  $W$  by calculating*

$$A \odot (U \oplus W) = A \odot (U \otimes I_m + I_n \otimes W).$$

# The Kronecker Sum

---

We can even check a program against more than two usage scenarios at the same time.

# The Kronecker Sum

---

We can even check a program against more than two usage scenarios at the same time. In order to be able to write this in a concise way, we introduce

$$\bigoplus_{x \in \mathcal{X}} x$$

similar to the sigma notation for standard sums.

# The Kronecker Sum

---

We can even check a program against more than two usage scenarios at the same time. In order to be able to write this in a concise way, we introduce

$$\bigoplus_{x \in \mathcal{X}} x$$

similar to the sigma notation for standard sums.

## Theorem

*With the definitions above, a program  $A$  can be checked against usage scenarios  $U_i$  where  $i = 1, \dots, k$  by calculating*

$$A \odot \left( \bigoplus_{i=1}^k U_i \right).$$



# The Kronecker Sum

---

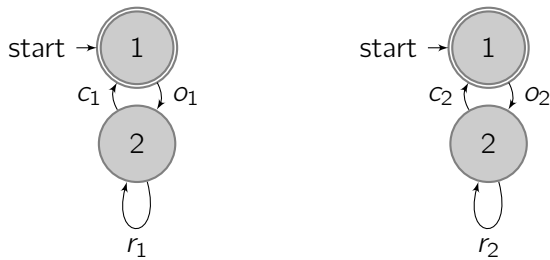


Abbildung: Graphical Representation of File Usage Scenarios  $U$  and  $W$

# The Kronecker Sum

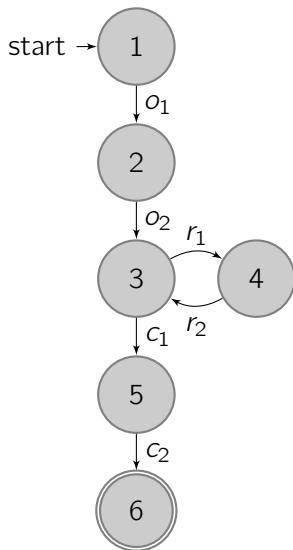


Abbildung: CFG of Program A

# The Kronecker Sum

---

$$U = \begin{pmatrix} \cdot & o_1 \\ c_1 & r_1 \end{pmatrix},$$

$$W = \begin{pmatrix} \cdot & o_2 \\ c_2 & r_2 \end{pmatrix},$$

and

$$A = \begin{pmatrix} \cdot & o_1 & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & o_2 & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & r_1 & c_1 & \cdot \\ \cdot & \cdot & r_2 & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & c_2 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}.$$

# The Kronecker Sum

$$\begin{aligned}U \oplus W &= U \otimes I_2 + I_2 \otimes W = \\ &\begin{pmatrix} \cdot & o_1 \\ c_1 & r_1 \end{pmatrix} \otimes \begin{pmatrix} 1 & \cdot \\ \cdot & 1 \end{pmatrix} + \begin{pmatrix} 1 & \cdot \\ \cdot & 1 \end{pmatrix} \otimes \begin{pmatrix} \cdot & o_2 \\ c_2 & r_2 \end{pmatrix} = \\ &\begin{pmatrix} \cdot & \cdot & o_1 & \cdot \\ \cdot & \cdot & \cdot & o_1 \\ c_1 & \cdot & r_1 & \cdot \\ \cdot & c_1 & \cdot & r_1 \end{pmatrix} + \begin{pmatrix} \cdot & o_2 & \cdot & \cdot \\ c_2 & r_2 & \cdot & \cdot \\ \cdot & \cdot & \cdot & o_2 \\ \cdot & \cdot & c_2 & r_2 \end{pmatrix} = \\ &\begin{pmatrix} \cdot & o_2 & o_1 & \cdot \\ c_2 & r_2 & \cdot & o_1 \\ c_1 & \cdot & r_1 & o_2 \\ \cdot & c_1 & c_2 & r_1 + r_2 \end{pmatrix}.\end{aligned}$$

# The Kronecker Sum

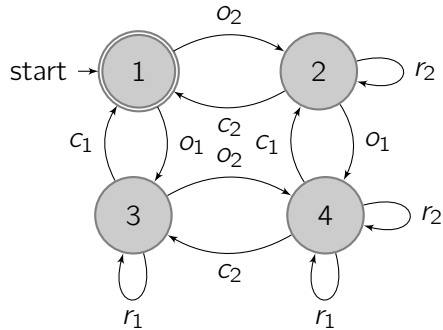


Abbildung: Graphical Representation of  $U \oplus W$



# The Kronecker Sum

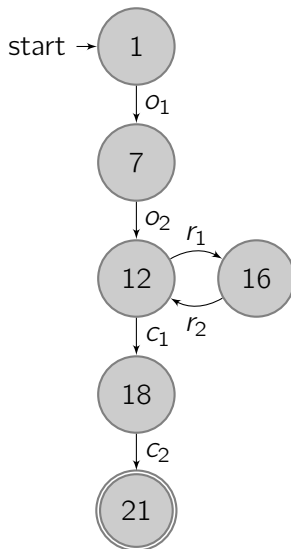


Abbildung: Graphical Representation of  $A \odot (U \oplus W)$

# The Kronecker Sum

---

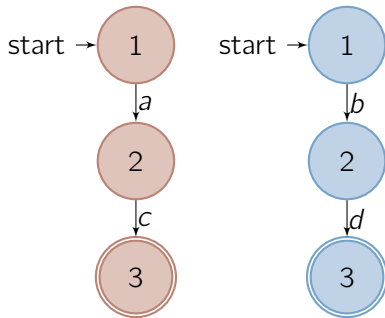


Abbildung: Our introductory example from a previous section



# Kronecker Sum

---

## Matrices

$$A = \begin{pmatrix} \cdot & a & \cdot \\ \cdot & \cdot & c \\ \cdot & \cdot & \cdot \end{pmatrix}$$

and

$$B = \begin{pmatrix} \cdot & b & \cdot \\ \cdot & \cdot & d \\ \cdot & \cdot & \cdot \end{pmatrix}$$

# Kronecker Sum

## Kronecker Product 1

$$A \otimes I_3 = \begin{pmatrix} \cdot & \cdot & \cdot & a & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & a & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & a & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & c & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & c & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & c \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix} .$$

# Kronecker Sum

## Kronecker Product 2

$$I_3 \otimes B = \begin{pmatrix} \cdot & b & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & d & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & b & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & d & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & b & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & d \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix} .$$

# Kronecker Sum

## Kronecker Sum

$$A \otimes I_3 + I_3 \otimes B = \begin{pmatrix} \cdot & b & \cdot & a & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & d & \cdot & a & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & a & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & b & \cdot & c & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & d & \cdot & c & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & c \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & b & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & d \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix} .$$

# The Kronecker Sum

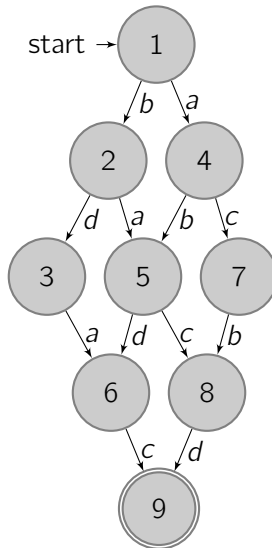


Abbildung: Resulting Interleavings Graph

# The Kronecker Sum

---

For more on Kronecker Algebra and its many applications see  
<https://kronalg.blieberger.at>.