

Programm- & Systemverifikation

Satisfiability Checking

Georg Weissenbacher

(some slides from Josef Widder)

184.741



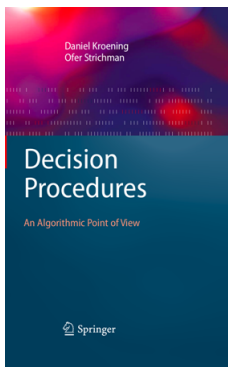
What happened so far

- ▶ How bugs come into being:
 - ▶ Fault – cause of an error (e.g., mistake in coding)
 - ▶ Error – *incorrect* state that may lead to failure
 - ▶ Failure – deviation from *desired* behaviour
- ▶ We specified *intended* behaviour using assertions
- ▶ We proved our programs correct (inductive invariants).
- ▶ We learned how to test programs.
- ▶ We heard about logical formalisms:
 - ▶ Propositional Logic
 - ▶ First Order Logic
 - ▶ Hoare Logic
- ▶ Last time we learned about Bounded Model Checking.

“Decision Procedures”

An Algorithmic Point of View

Daniel Kröning, Ofer Strichman



- ▶ Chapter 2.2:
SAT Solvers
- ▶ Available in
“Hauptbibliothek”

Propositional Logic:

$$\begin{aligned} \textit{formula} & ::= \textit{formula} \wedge \textit{formula} \mid \textit{formula} \vee \textit{formula} \mid \\ & \quad \neg \textit{formula} \mid (\textit{formula}) \mid \textit{atom} \\ \textit{atom} & ::= \textit{propositional identifier} \mid \textit{constant} \\ \textit{constant} & ::= \textit{true} \mid \textit{false} \end{aligned}$$

- ▶ Goal:
 - ▶ Find satisfying assignment or
 - ▶ show unsatisfiability
- ▶ Soundness: Decision Procedure gives correct answer
- ▶ Completeness: Decision Procedure always finds an answer

Warm-up: SAT or UNSAT?

$$(a \vee b) \wedge \neg a \wedge \neg b$$

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UNSAT ... contains all clauses of previous formula

Motivation: Why Do We Need SAT Solvers?

- ▶ SAT is the canonical NP-complete problem
 - ▶ Other problems in NP can be reduced to SAT
 - ▶ Unless $P = NP$, there is no efficient solution

Motivation: Applications of SAT Solvers in Verification

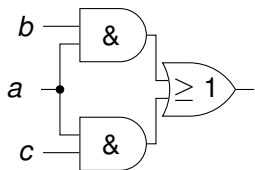
- ▶ Test Case Generation
- ▶ Bounded Model Checking
- ▶ Equivalence Checking

Checking Equivalence of Circuits

Show that, e.g., optimized circuit has the same functionality

Checking Equivalence of Circuits

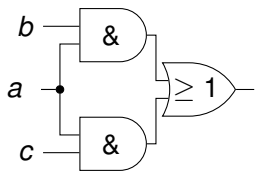
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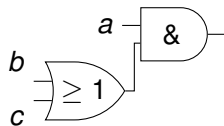
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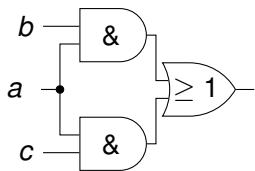
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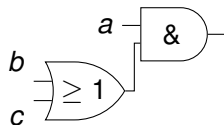
$$C_2 \equiv a \wedge (b \vee c)$$

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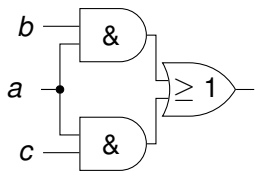


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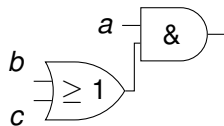
Are C_1 and C_2 functionally equivalent?

Checking Equivalence of Circuits

Show that, e.g., optimized circuit has the same functionality



$$C_1 \equiv (a \wedge b) \vee (a \wedge c)$$



$$C_2 \equiv a \wedge (b \vee c)$$

Are C_1 and C_2 functionally equivalent?

Is $\neg(C_1 \Leftrightarrow C_2)$ unsatisfiable?

There is no assignment to a , b , and c , such that C_1 and C_2 yield different truth values.

Test Case/Pattern Generation

- ▶ Inject bug in software (mutation) or fault in hardware
 - ▶ e.g., variable or wire replaced with a constant
- ▶ Yields two versions of encoding of software/hardware:
 - ▶ Original program/circuit C
 - ▶ Faulty program/circuit C'
- ▶ If $(C \oplus C')$ is satisfiable
 - ▶ satisfying assignment corresponds to test inputs
 - ▶ test inputs *reveal* fault (if present in program/circuit)

Conjunctive Normal Form

- ▶ CNF formula: A conjunction of clauses (product of sums)

$$\bigwedge_i \bigvee_j \ell_{i,j}, \quad \ell_{i,j} \in \{a, \neg a \mid a \in \text{Variables}\}$$

e.g.,

$$\neg a_1 \wedge (a_1 \vee \neg a_2) \wedge (\neg a_1 \vee a_2) \wedge a_1$$

- ▶ Remember:
 - ▶ $\bigvee_{\ell \in \emptyset} \ell \equiv \text{false}$ (we use \square to denote the empty clause)
- ▶ Alternative (more compact) notation:

$$(\bar{a}_1) (a_1 \bar{a}_2) (\bar{a}_1 a_2) (a_1)$$

- ▶ Obtained through Tseitin transformation (see lecture on logic)

Tseitin's Algorithm Revisited: Example

$$(a \Rightarrow (c \wedge d)) \vee (b \Rightarrow (c \wedge e))$$

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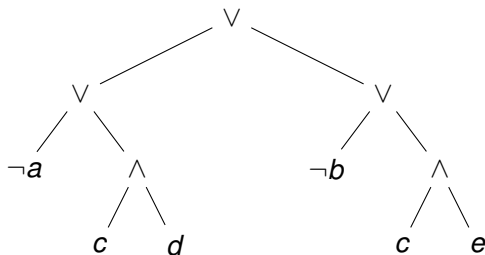
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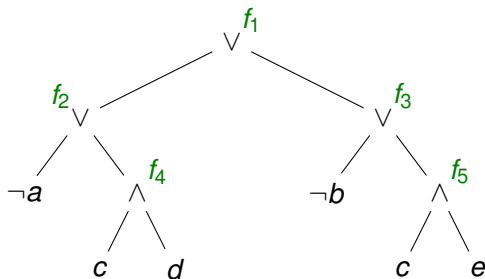
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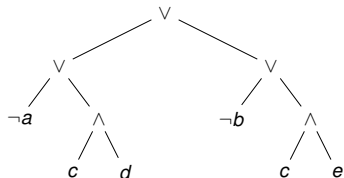
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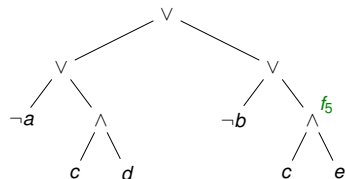
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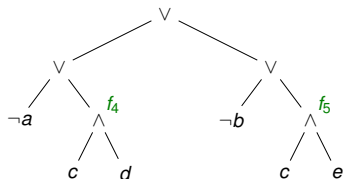
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$$(\neg f_5 \vee c) \wedge (\neg f_5 \vee e) \wedge (\neg c \vee \neg e \vee f_5)$$

Example for Tseitin continued

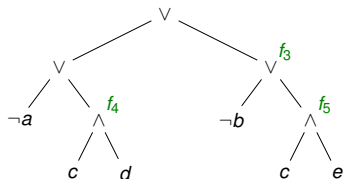
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$$\begin{aligned} & \wedge \\ & (\neg f_4 \vee c) \wedge (\neg f_4 \vee d) \wedge (\neg c \vee \neg d \vee f_4) \\ & \wedge \\ & (\neg f_5 \vee c) \wedge (\neg f_5 \vee e) \wedge (\neg c \vee \neg e \vee f_5) \end{aligned}$$

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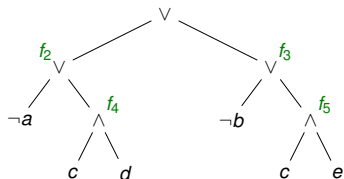
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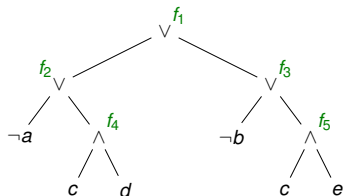
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Quantifier Expansion

- ▶ Is there a *satisfying* assignment?
 - ▶ Naïve algorithm for n variables: $O(2^n)$
- ▶ Let's look at a single variable y first:

$$(x \vee y) \wedge (z \vee \neg y)$$

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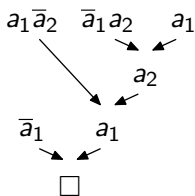
Resolution Principle

- ▶ Let C, D be clauses (disjunctions of literals)

$$\frac{(C \vee a) \quad (D \vee \bar{a})}{C \vee D} \quad [\text{Res}]$$

- ▶ For instance:

$$(\bar{a}_1) (a_1 \bar{a}_2) (\bar{a}_1 a_2) (a_1)$$



Unit Resolution

- ▶ In particular:

$$\frac{(C \vee a) \quad (\bar{a})}{C} \quad [\text{Res}]$$

- ▶ “Unit Clause Rule”
- ▶ Example revisited:

$$(\bar{a}_1) \quad (a_1 \bar{a}_2) \quad (\bar{a}_1 a_2) \quad (a_1)$$

$$\begin{array}{ccc} \bar{a}_1 a_2 & & a_1 \\ & \searrow & \swarrow \\ & a_2 & \end{array}$$

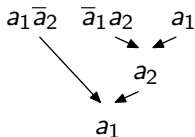
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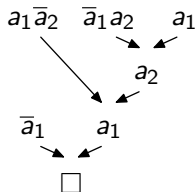
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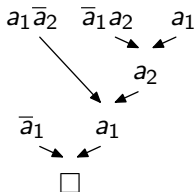
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- ▶ Unit clause *propagation*: Efficient

Decision Making

- ▶ What if there are no unit clauses?
 - ▶ Progress by making decisions about variables:

$$(a_1 \bar{a}_2)$$
$$\{a_1 \mapsto 1, \dots\}$$

Decision Making

- ▶ What if there are no unit clauses?
 - ▶ Progress by making decisions about variables:

$$(a_1 \bar{a}_2) \\ \{a_1 \mapsto 1, \dots\}$$

- ▶ Partial assignment: Not all variables assigned

$$\{x_1 \mapsto 1, x_2 \mapsto 0, x_4 \mapsto 1\}$$

- ▶ $(x_1 \vee x_3 \vee \neg x_4)$ is *satisfied*
One or more literal satisfied (clause can be ignored)
- ▶ $(\neg x_1 \vee x_2)$ is *conflicting*:
All literals assigned but not satisfied
- ▶ $(\neg x_1 \vee \neg x_4 \vee x_3)$ is *unit*:
All but one literal assigned, but not satisfied
- ▶ $(\neg x_1 \vee x_3 \vee x_5)$ is *unresolved*

Decision Levels

- ▶ Decision may result in *unit clauses*

$$\{x_1 \mapsto 1, x_4 \mapsto 1\}$$
$$(\neg x_1 \vee \neg x_4 \vee x_3)$$

- ▶ Results in unit clause:

- ▶ $\{x_1 \mapsto 1, x_4 \mapsto 1\}$ AND $(\neg x_1 \vee \neg x_4 \vee x_3)$ implies x_3
- ▶ Antecedent of x_3 is $(\neg x_1 \vee \neg x_4 \vee x_3)$
- ▶ Leads to unit propagation!

- ▶ Each decision is associated with a *decision level*

$$\underbrace{\{x_1 \mapsto 1\}}_1, \underbrace{\{x_4 \mapsto 1\}}_2, \dots\}$$

- ▶ Implications of a decision associated with same decision level:
 - ▶ x_4 and x_3 above have decision level 2,
denoted by $\neg x_4@2$ and $x_3@2$

Decision Levels (continued)

dl **Assignment**

0 –

Clauses

$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$

Decision Levels (continued)

dl **Assignment**

0 –

1 $\{x_1 \mapsto 1\}$

Clauses

$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$

$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2) \quad x_1 @ 1$

Decision Levels (continued)

<i>dl</i>	Assignment	Clauses	
0	–	$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$	
1	$\{x_1 \mapsto 1\}$	$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$	$x_1@1$
2	$\{x_1 \mapsto 1, x_4 \mapsto 1\}$	$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$	$x_4@2$
	$\{x_1 \mapsto 1, x_4 \mapsto 1, x_3 \mapsto 1\}$	$(x_3)(\bar{x}_3 \bar{x}_2)$	$x_3@2$

Decision Levels (continued)

<i>dl</i>	Assignment	Clauses	
0	–	$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$	
1	$\{x_1 \mapsto 1\}$	$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$	$x_1 @1$
2	$\{x_1 \mapsto 1, x_4 \mapsto 1\}$	$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$	$x_4 @2$
	$\{x_1 \mapsto 1, x_4 \mapsto 1, x_3 \mapsto 1\}$	$(x_3)(\bar{x}_3 \bar{x}_2)$	$x_3 @2$
	$\{x_1 \mapsto 1, x_4 \mapsto 1, x_3 \mapsto 1, x_2 \mapsto 0\}$	(\bar{x}_2)	$\neg x_2 @2$

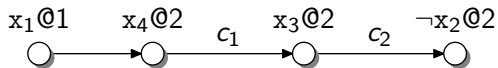
Decision Levels (continued)

<i>dl</i>	Assignment	Clauses	
0	–	$(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$	
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	$\{x_1 \mapsto 1, x_4 \mapsto 1, x_3 \mapsto 1\}$	$(x_3)(\bar{x}_3 \bar{x}_2)$	$x_3 @2$
	$\{x_1 \mapsto 1, x_4 \mapsto 1, x_3 \mapsto 1, x_2 \mapsto 0\}$	(\bar{x}_2)	$\neg x_2 @2$

► $\{x_1 \mapsto 1, x_4 \mapsto 1, x_3 \mapsto 1, x_2 \mapsto 0\}$ satisfies $(\bar{x}_1 \bar{x}_4 x_3)(\bar{x}_3 \bar{x}_2)$

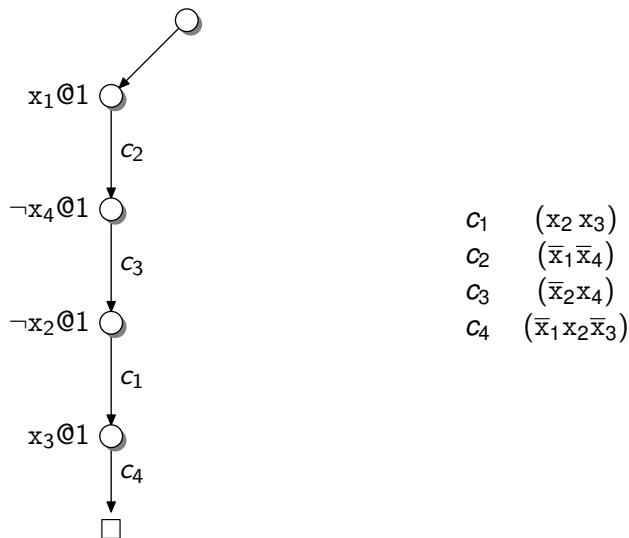
Boolean Constraint Propagation, Implication Graph

$$c_1 \equiv (\bar{x}_1 \bar{x}_4 x_3), \quad c_2 \equiv (\bar{x}_3 \bar{x}_2)$$

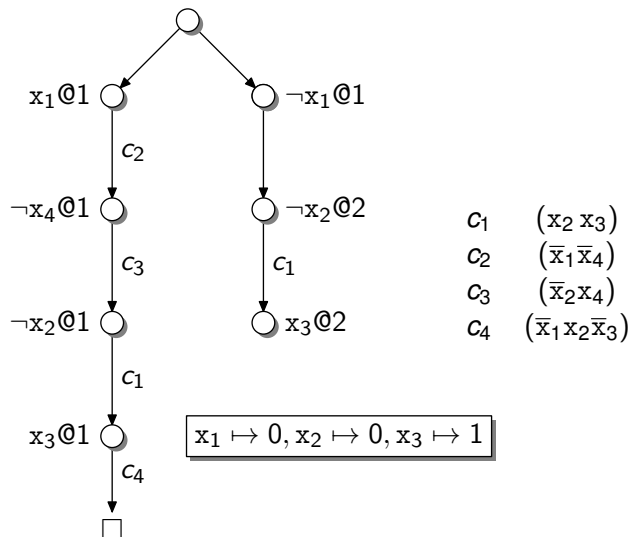


- ▶ Nodes labelled with *decisions*
- ▶ Edges labelled with *antecedents*

What if a decision is wrong?



What if a decision is wrong?



Davis-Putnam-Loveland-Logeman (DPLL)

- ▶ Decide
Choose a variable and make a decision
- ▶ Propagate
Propagate implications
- ▶ Backtrack
“Undo” decisions which lead to conflict

Conflict-Driven Backtracking

- ▶ How can we do *systematic* backtracking?

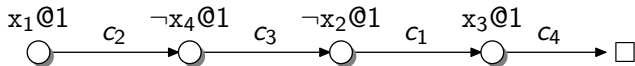
Definition (Partial Implication Graph)

Sub-graph of an implication graph illustrating binary constraint propagation (BCP) at a specific implication level

Definition (Conflict Graph)

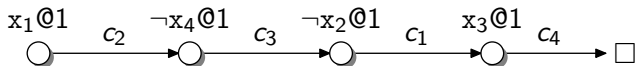
An implication graph in which BCP has reached a conflict

$$c_1 \equiv (x_2 x_3), c_2 \equiv (\bar{x}_1 \bar{x}_4), c_3 \equiv (\bar{x}_2 x_4), c_4 \equiv (\bar{x}_1 x_2 \bar{x}_3)$$



Conflict-Driven Backtracking, Learning

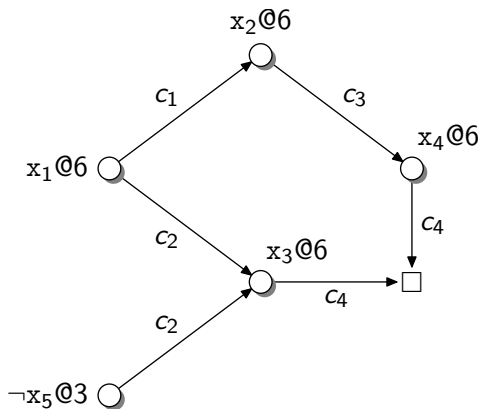
$$c_1 \equiv (x_2 x_3), c_2 \equiv (\bar{x}_1 \bar{x}_4), c_3 \equiv (\bar{x}_2 x_4), c_4 \equiv (\bar{x}_1 x_2 \bar{x}_3)$$



- ▶ Analyse conflict
- ▶ Add *learnt conflict clause* ((\bar{x}_1) in our example)
- ▶ Backtrack
 - ▶ to highest decision level in conflict clause that's not the current decision level
 - ▶ to 0, if we learnt a unit clause

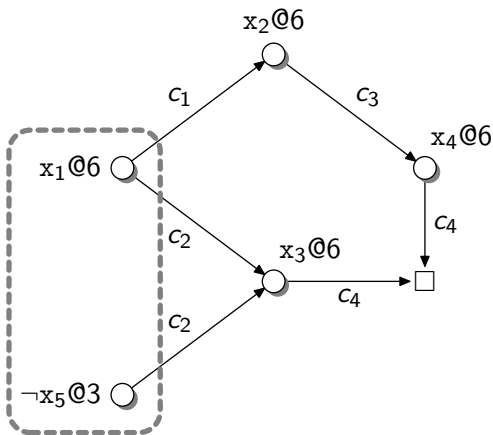
Example: Learning Conflict Clauses

$$\begin{aligned}C_1 &= (\bar{x}_1 x_2) \\C_2 &= (\bar{x}_1 x_3 x_5) \\C_3 &= (\bar{x}_2 x_4) \\C_4 &= (\bar{x}_3 \bar{x}_4)\end{aligned}$$



Example: Learning Conflict Clauses

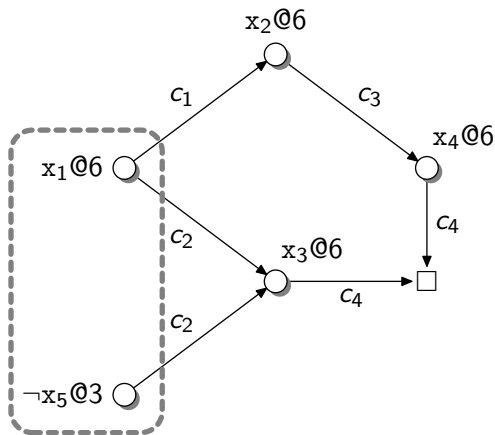
$$\begin{aligned}c_1 &= (\bar{x}_1 x_2) \\c_2 &= (\bar{x}_1 x_3 x_5) \\c_3 &= (\bar{x}_2 x_4) \\c_4 &= (\bar{x}_3 \bar{x}_4)\end{aligned}$$



► Conflict clause: $(\bar{x}_1 x_5)$

Example: Learning Conflict Clauses

$$\begin{aligned}c_1 &= (\bar{x}_1 x_2) \\c_2 &= (\bar{x}_1 x_3 x_5) \\c_3 &= (\bar{x}_2 x_4) \\c_4 &= (\bar{x}_3 \bar{x}_4)\end{aligned}$$



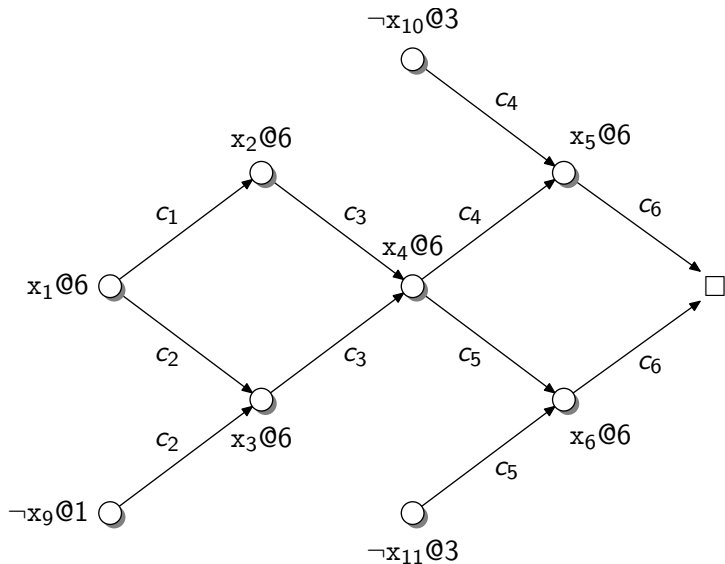
- ▶ Conflict clause: $(\bar{x}_1 x_5)$
- ▶ Backtracking level: 3
 - ▶ Erase all decisions from decision level 4 onwards

Asserting Clauses

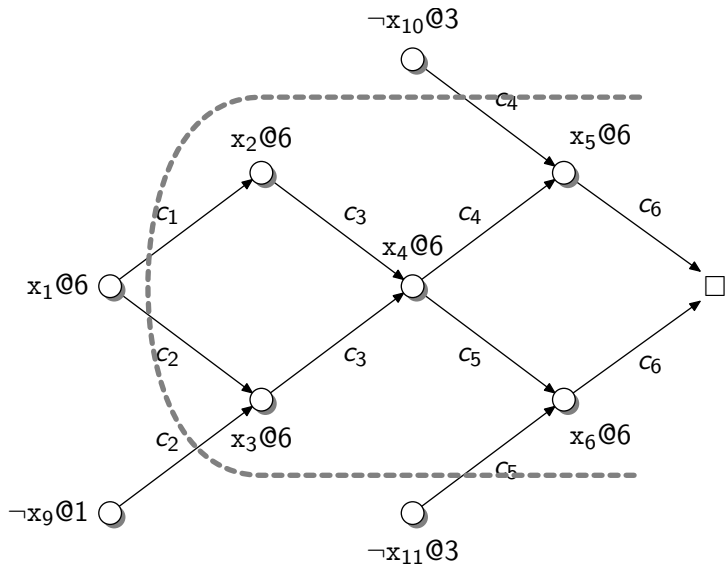
$$\begin{array}{l} c_1 = (\bar{x}_1 x_2) \\ c_2 = (\bar{x}_1 x_3 x_5) \\ c_3 = (\bar{x}_2 x_4) \\ c_4 = (\bar{x}_3 \bar{x}_4) \\ \hline c_5 = (\bar{x}_1 x_5) \end{array}$$

- ▶ We backtracked to decision level of x_5
- ▶ Since $x_5 \mapsto 0$, $(\bar{x}_1 x_5)$ forces an immediate implication
- ▶ Such a clause is called **asserting clause**

Choosing Conflict Clauses

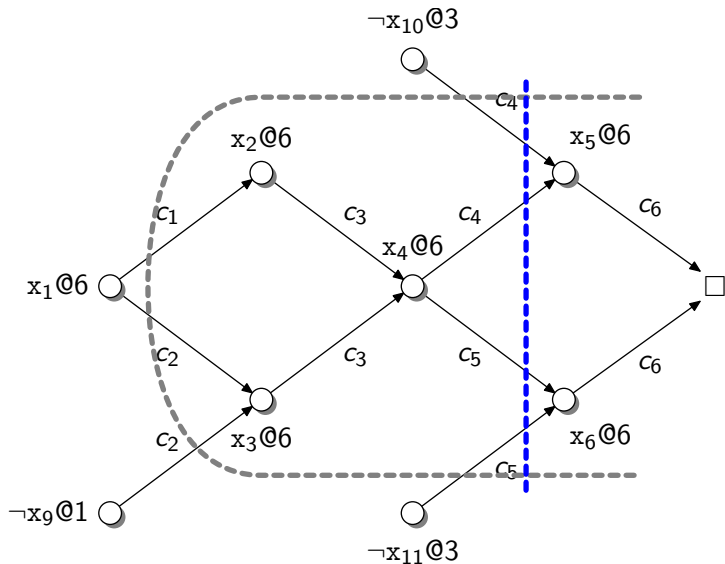


Choosing Conflict Clauses



1.) $(x_{10} \bar{x}_1 x_9 x_{11})$

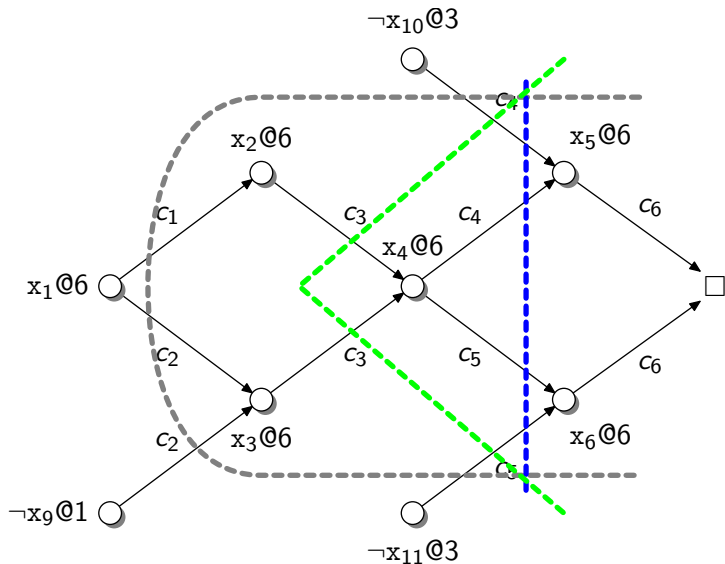
Choosing Conflict Clauses



1.) $(x_{10} \bar{x}_1 x_9 x_{11})$

2.) $(x_{10} \bar{x}_4 x_{11})$

Choosing Conflict Clauses



1.) $(x_{10} \bar{x}_1 x_9 x_{11})$

2.) $(x_{10} \bar{x}_4 x_{11})$

3.) $(x_{10} \bar{x}_2 \bar{x}_3 x_{11})$

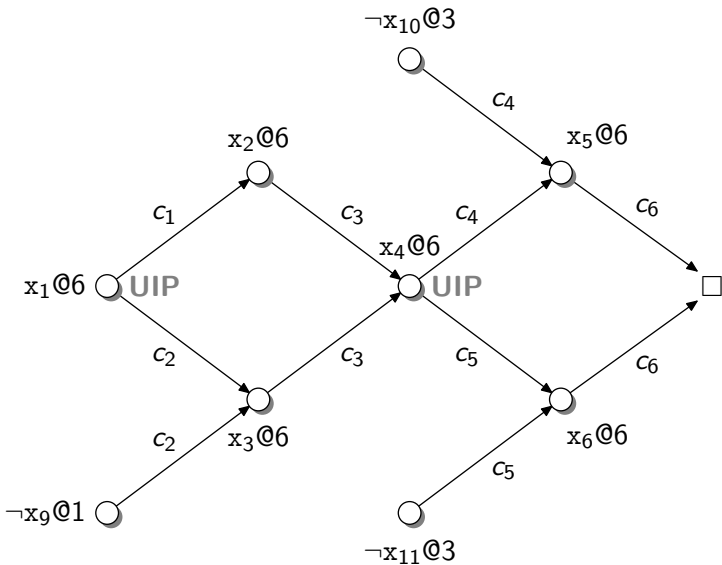
Definition (Unique Implication Point)

Any node (other than the conflict node) in the partial conflict graph which is on *all paths*

- ▶ from the decision node
- ▶ to the conflict node

Note: The decision node is a UIP by definition.

Conflict Clauses: Unique Implication Point (ctd.)

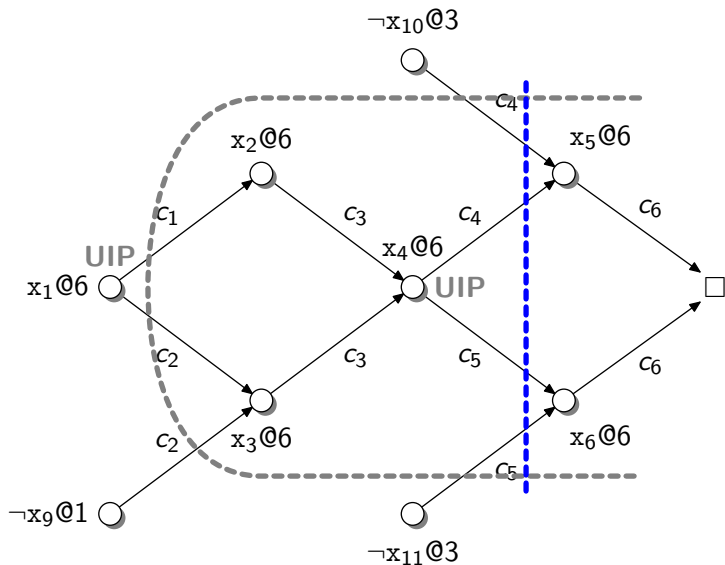


Definition (First Unique Implication Point)

The UIP that's closest to the conflict node

- ▶ Choose conflict clause that contains *First UIP* as only literal at the current decision level
- ▶ Advantages:
 - ▶ Clause is an assertion clause
 - ▶ Backtracks to *lowest decision level*
Why? Clause with First UIP “*subsumes*” other UIPs

Conflict Clauses: Unique Implication Point (ctd.)



1.) $(x_{10} \bar{x}_1 x_9 x_{11})$

2.) $(x_{10} \bar{x}_4 x_{11})$

Conflict Clauses and Resolution

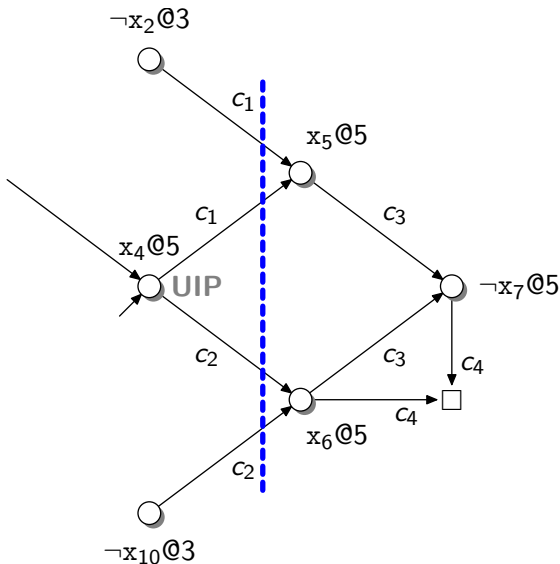
$$C_1 = (\bar{x}_4 \ x_2 \ x_5)$$

$$C_2 = (\bar{x}_4 \ x_{10} \ x_6)$$

$$C_3 = (\bar{x}_5 \ \bar{x}_6 \ \bar{x}_7)$$

$$C_4 = (\bar{x}_6 \ x_7)$$

$$C_5 = (x_2 \ \bar{x}_4 \ x_{10})$$



Conflict Clauses and Resolution

$$c_1 = (\bar{x}_4 x_2 x_5)$$

$$c_2 = (\bar{x}_4 x_{10} x_6)$$

$$c_3 = (\bar{x}_5 \bar{x}_6 \bar{x}_7)$$

$$c_4 = (\bar{x}_6 x_7)$$

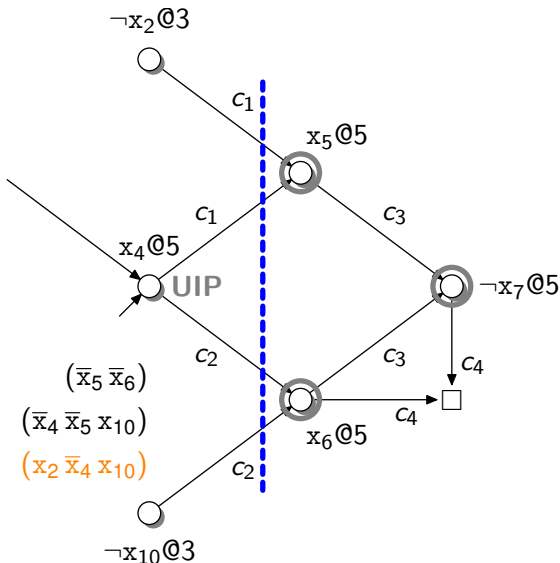
$$c_5 = (x_2 \bar{x}_4 x_{10})$$

Order: x_4, x_5, x_6, x_7

$$t_1 = \text{Res}(c_4, c_3, x_7) = (\bar{x}_5 \bar{x}_6)$$

$$t_2 = \text{Res}(t_1, c_2, x_6) = (\bar{x}_4 \bar{x}_5 x_{10})$$

$$t_3 = \text{Res}(t_2, c_1, x_5) = (x_2 \bar{x}_4 x_{10})$$



Conflict Clauses and Resolution

- ▶ Start with currently conflicting clause (c_4 in example)
- ▶ Choose last assigned literal (x_7 in example)
- ▶ x_7 follows from c_3
- ▶ Phase of x_7 in c_4 differs from c_3
- ▶ $t_1 = \text{Res}(c_4, c_3, x_7)$
- ▶ Iterate until we reach UIP

(i.e., t_i contains UIP as single literal at current decision level)

In our example:

$$t_1 = \text{Res}(c_4, c_3, x_7) = (\bar{x}_5 \bar{x}_6)$$

$$t_2 = \text{Res}(t_1, c_2, x_6) = (\bar{x}_4 \bar{x}_5 x_{10})$$

$$t_3 = \text{Res}(t_2, c_1, x_5) = (x_2 \bar{x}_4 x_{10})$$

Conflict Clauses

- ▶ Each conflict clause consequence
 - ▶ of F and
 - ▶ previously derived conflict clauses
- ▶ Derived using resolution
- ▶ Therefore, conflict clause is implied by original CNF formula F
- ▶ Therefore, SAT-solver can be used to **find resolution proofs!**

- ① If conflict at decision level 0 \rightarrow UNSAT
- ② Repeat:
 - ① if all variables assigned return SAT
 - ② Make decision
 - ③ Propagate constraints
 - ④ No conflict? Go to ①
 - ⑤ If decision level = 0 return UNSAT
 - ⑥ Analyse conflict
 - ⑦ Add conflict clause
 - ⑧ Backtrack and go to ③

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 - ⑥ Analyse conflict
 - ⑦ Add conflict clause
 - ⑧ Backtrack and go to ③

Termination argument:

- ▶ Solver never enters same decision level with same partial assignment

```
c A sample .cnf file
p cnf 3 2
1 -3 0
2 3 -1 0
```

DIMACS = Discrete Mathematics and Theoretical Computer Science,
a collaboration Rutgers & Princeton, to determine practical algorithm
performance on computationally hard problems

Unsatisfiable Core

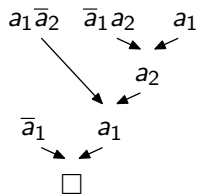
- ▶ If instance unsatisfiable, SAT-solver derives \square
- ▶ Follow resolution edges starting from \square
 - ▶ we obtain a resolution refutation proof
 - ▶ does *not* necessarily contain all clauses visited during SAT-run
 - ▶ represents *unsatisfiable core*

Definition (Unsatisfiable Core)

Any unsatisfiable subset of the original set of clauses

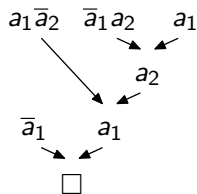
Variable Order

- ▶ Does the order in which we assign variables matter?
- ▶ How about the values we choose?



Variable Order

- ▶ Does the order in which we assign variables matter?
- ▶ How about the values we choose?



Probably the most important element in SAT solving!

Dynamic Largest Individual Sum –

choose assignment s.t. number of satisfied clauses is maximised

- ▶ p_x ... # of unresolved clauses containing x
- ▶ n_x ... # of unresolved clauses containing \bar{x}
- ▶ Let x be variable for which p_x is maximal
- ▶ Let y be variable for which n_y is maximal
- ▶ If $p_x > n_y$ choose $x \mapsto 1$
- ▶ Otherwise, choose $y \mapsto 0$

Disadvantage: High overhead

Variable State Independent Decaying Sum –

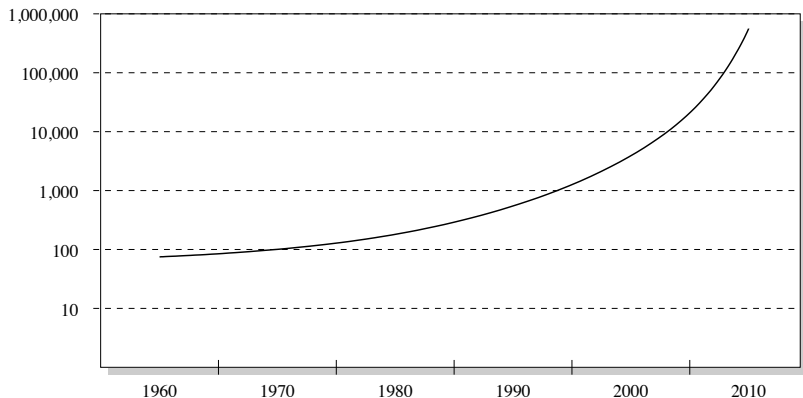
favour literals in recently added conflict clauses

- ▶ Each literal has counter initialised to 0
- ▶ When clause is added, literals in clause are *boosted*
- ▶ Periodically, all counters divided by constant
- ▶ Choose unassigned literal with highest counter

- ▶ Implemented in CHAFF
 - ▶ Maintain list of unassigned literals sorted by counter
 - ▶ Update list when adding conflict clauses
 - ▶ Decision in $O(1)$
- ▶ Improved performance by order of magnitude

Performance of SAT Solvers

- ▶ Scales to hundreds of thousands of variables
 - ▶ for “benign” problems
 - ▶ challenges:
 - ▶ *pigeon hole problems* (size of resolution proof exponential)
 - ▶ chains of \oplus



BDDs vs SAT

	BDD	SAT
Variables	Hundreds	hundreds of thousands
Complexity	PSPACE-complete	NP-complete
Assignments	$O(n)$	SAT-run
Canonical	Yes	No
Equality check	$O(1)$ (hashing)	SAT-run ($F \oplus G$)
Quantifier elimination	Yes	Co-Factoring

- ▶ Efficient SAT checking for propositional logic
- ▶ Next time: Satisfiability Modulo Theories (SMT)
 - ▶ Theory-specific reasoning